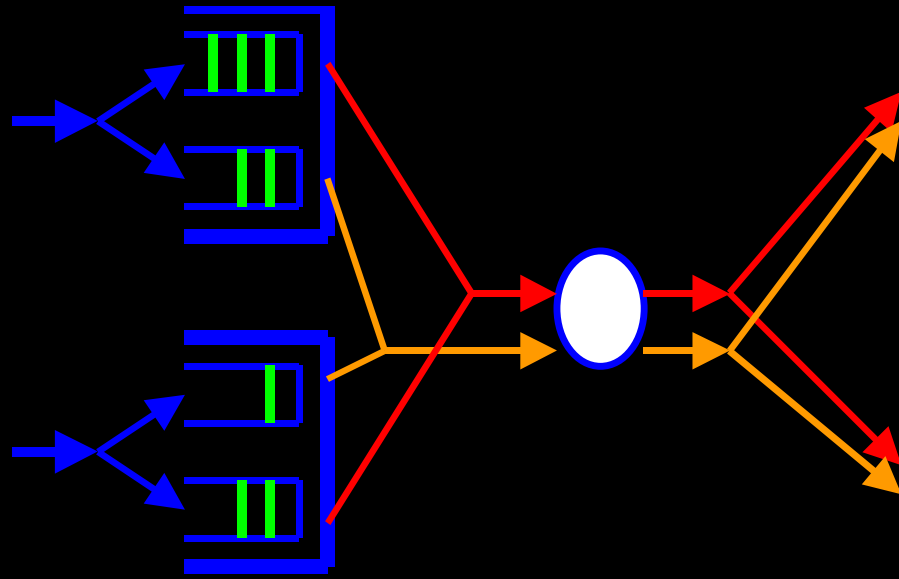


Stochastic Processing Networks



Ruth J. Williams

University of California, San Diego

<http://www.math.ucsd.edu/~williams>

Maurice Belz (1897-1975)

Founding Professor of Statistics, University of Melbourne, 1955-1963



National Library of Australia

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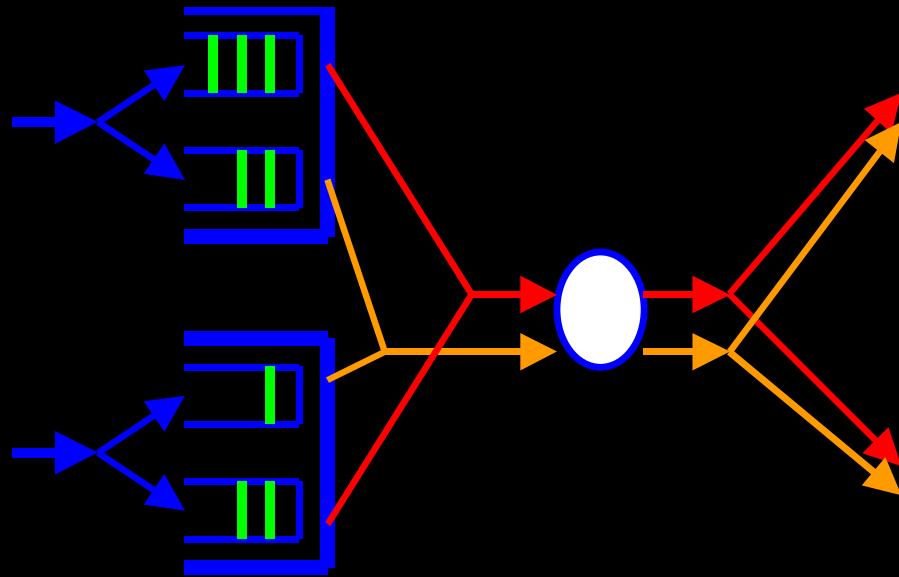


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nla.pic-an23208394-v

Statistical Methods for the Process Industries (1973)

Stochastic Processing Networks: What, Why and How?



Ruth J. Williams

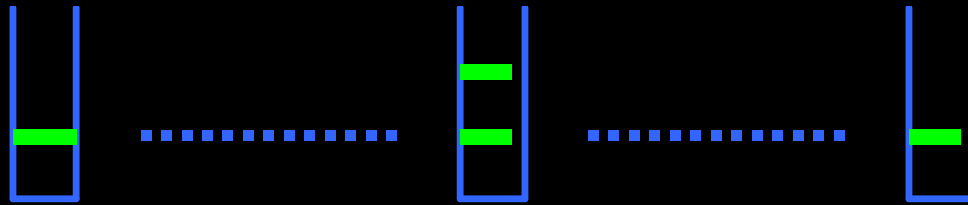
University of California, San Diego

<http://www.math.ucsd.edu/~williams>

OUTLINE

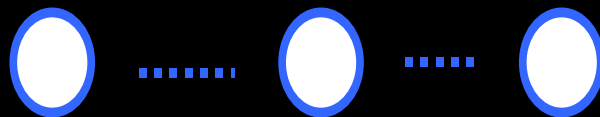
- What is a Stochastic Processing Network?
- Applications
- Questions
- A Simple Example
- Approximations
- Perspective
- Two Motivating Examples
- Main Topics for Remaining Lectures

Stochastic Processing Networks (cf. Harrison '00)



\mathbb{I} buffers
(classes)

\mathbb{J} activities

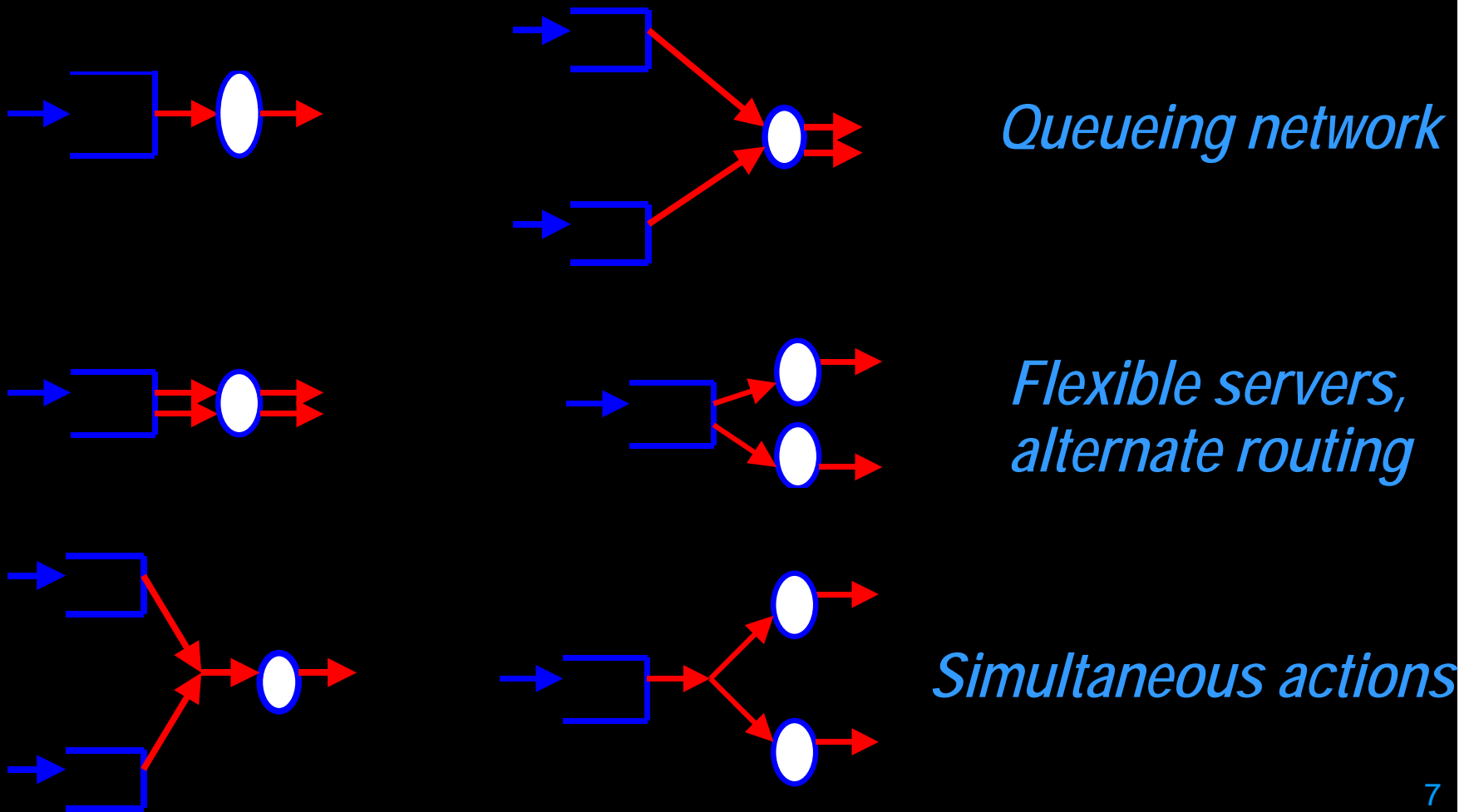


\mathbb{K} servers
(resources)

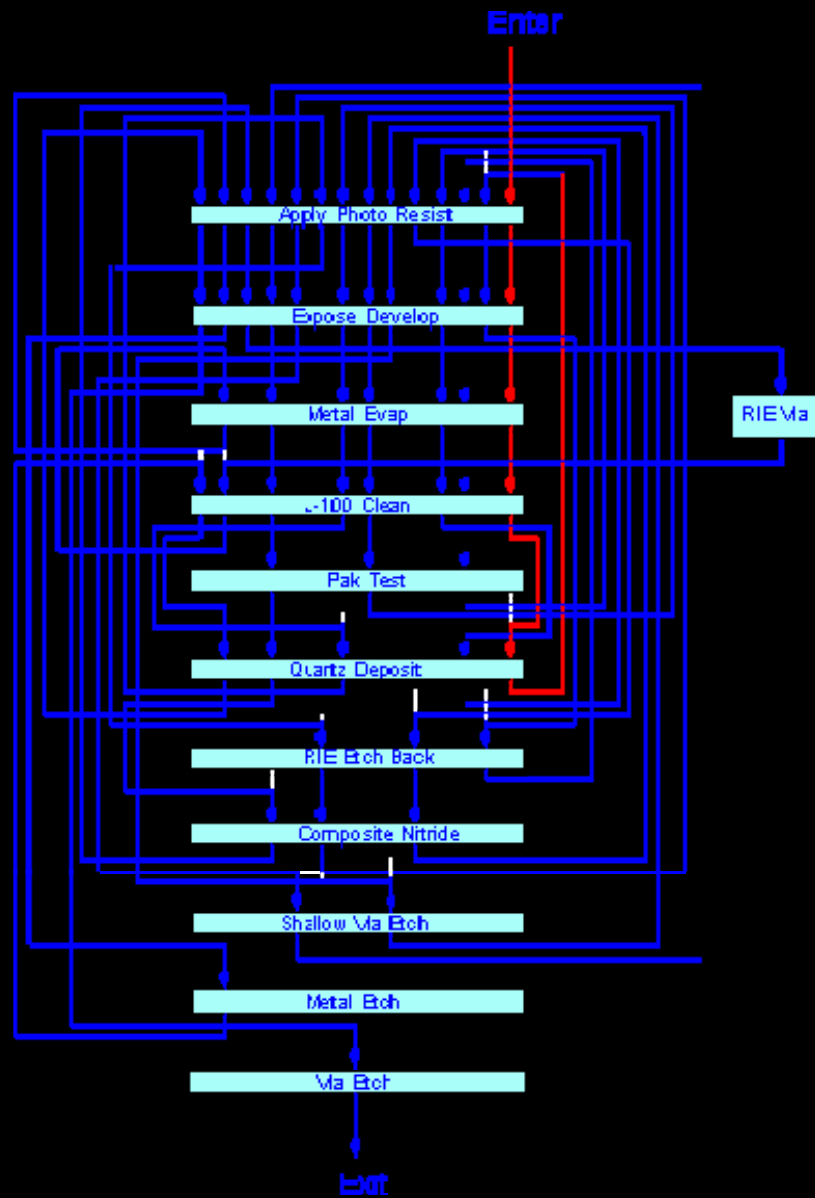
An **activity** consumes from certain classes, produces for certain (possibly different) classes, and uses certain servers.

Stochastic Processing Networks

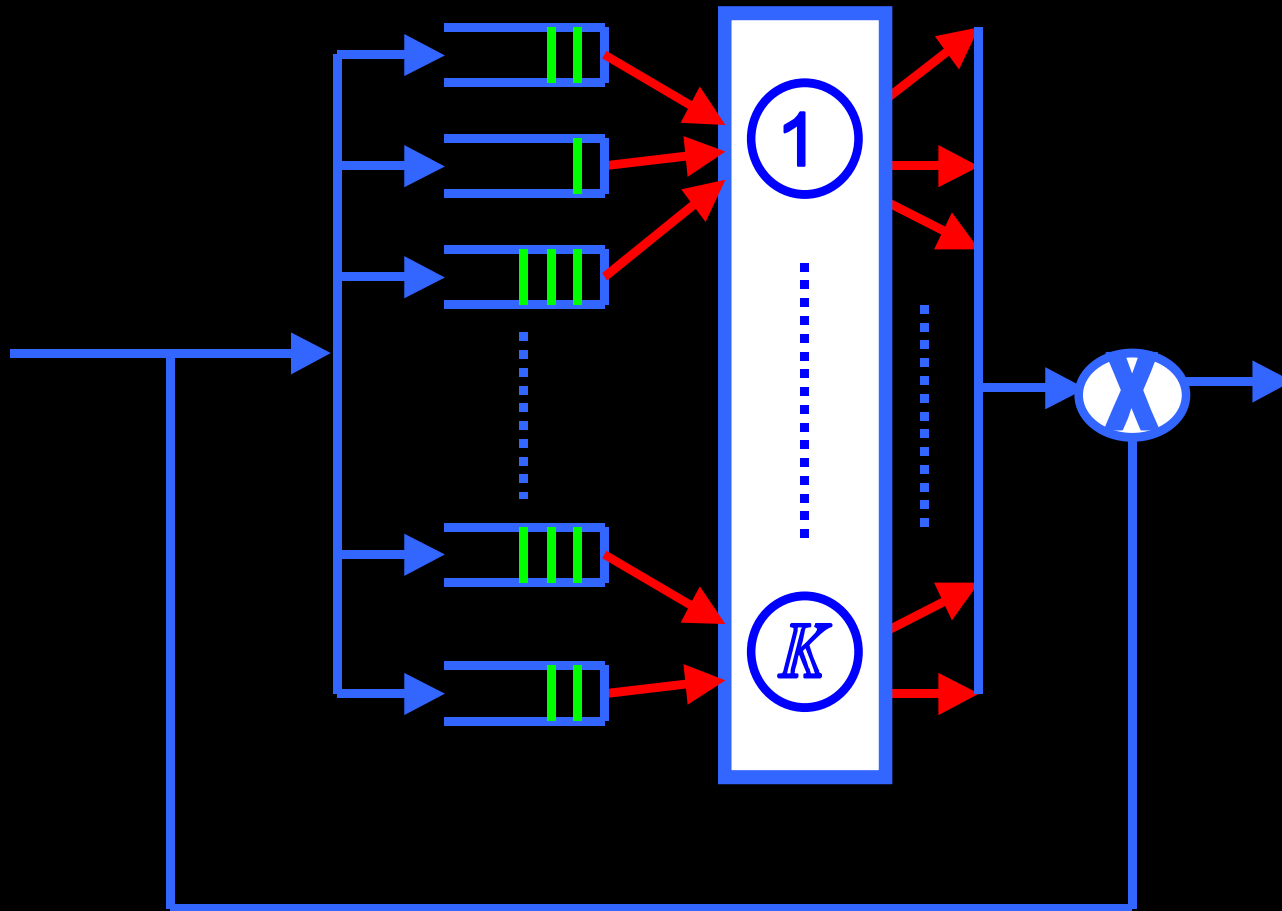
SPN Activities are Very General



Semiconductor Wafer Fab: P. R. Kumar



Multiclass Queueing Network



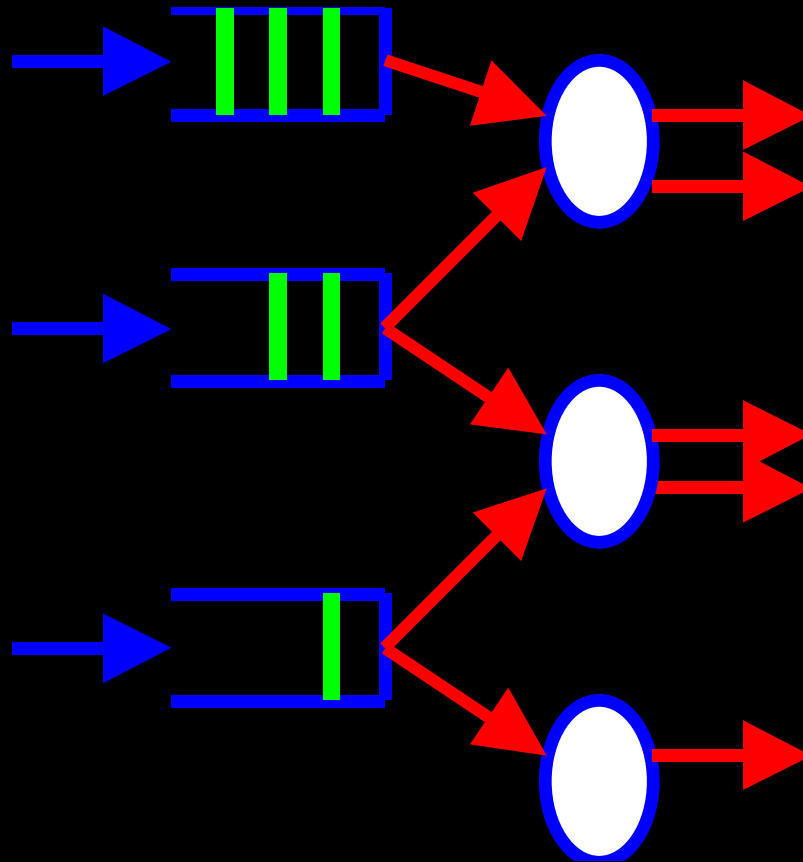
Call Center: First Direct (branchless retail banking)

Larreche et al., INSEAD '97 (see also Gans, Koole, Mandelbaum '93)

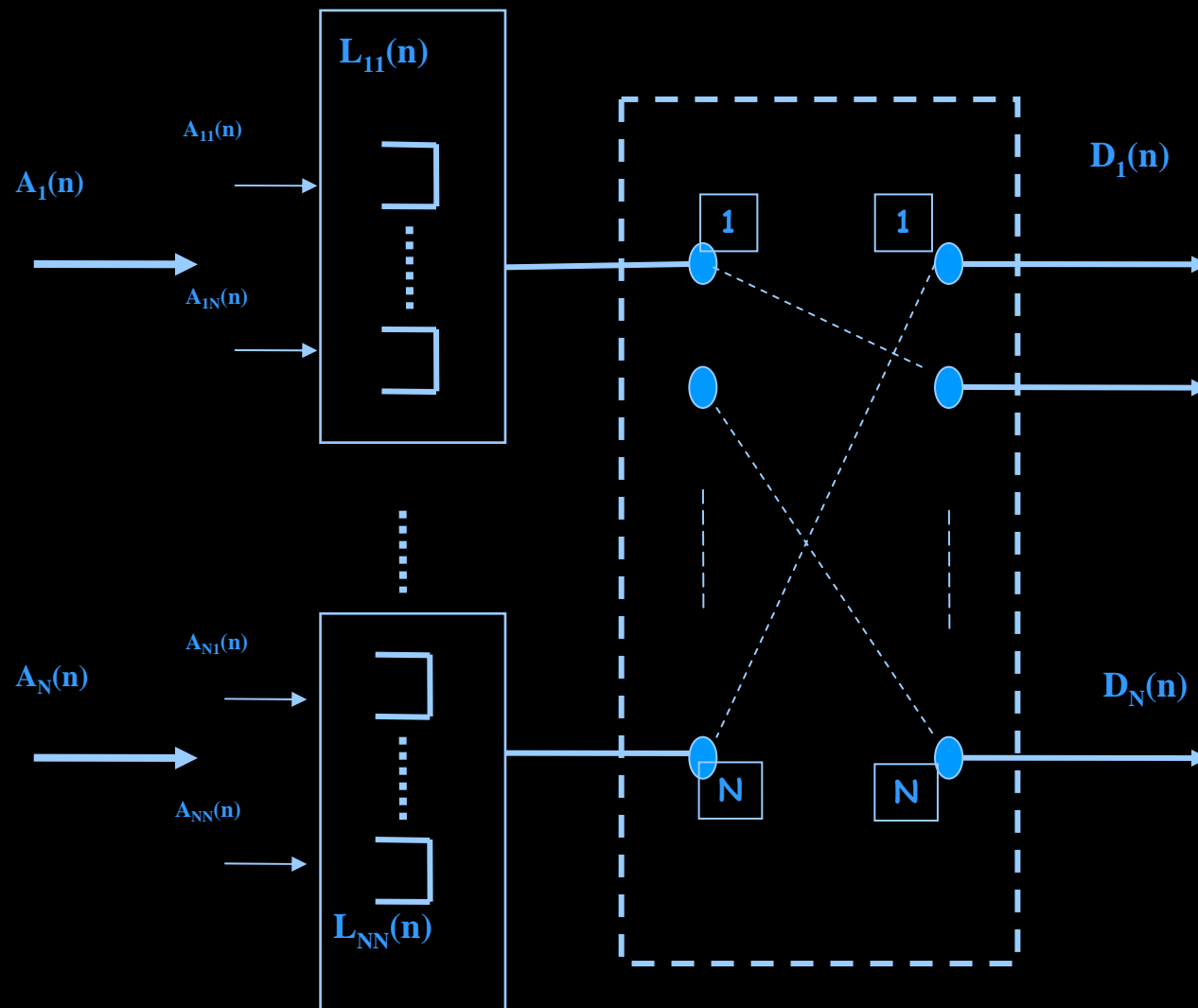


Differentiated Service Center

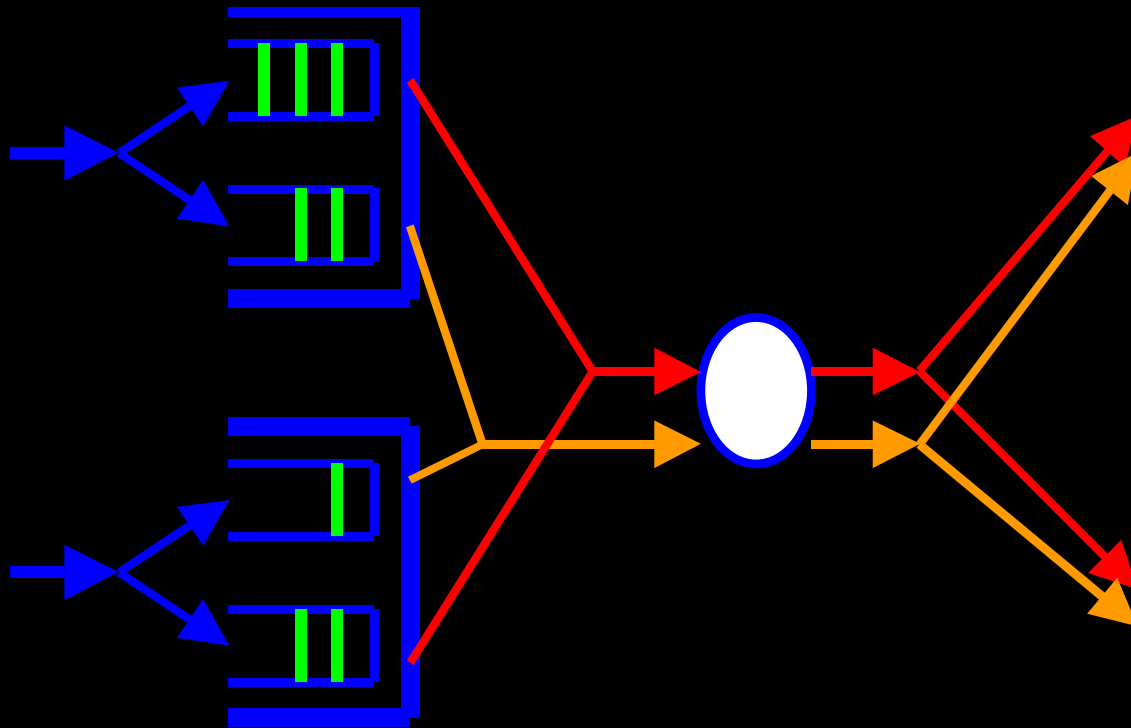
(Parallel server system, alternate routing)



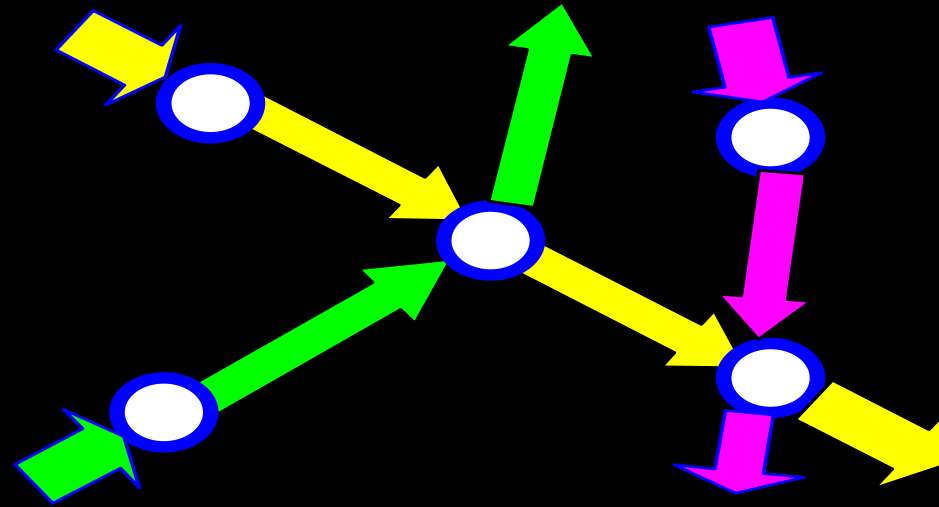
NxN Input Queued Packet Switch: Prabhakar



2x2 Input Queued Packet Switch



Data Network (Roberts and Massoulie, '00)

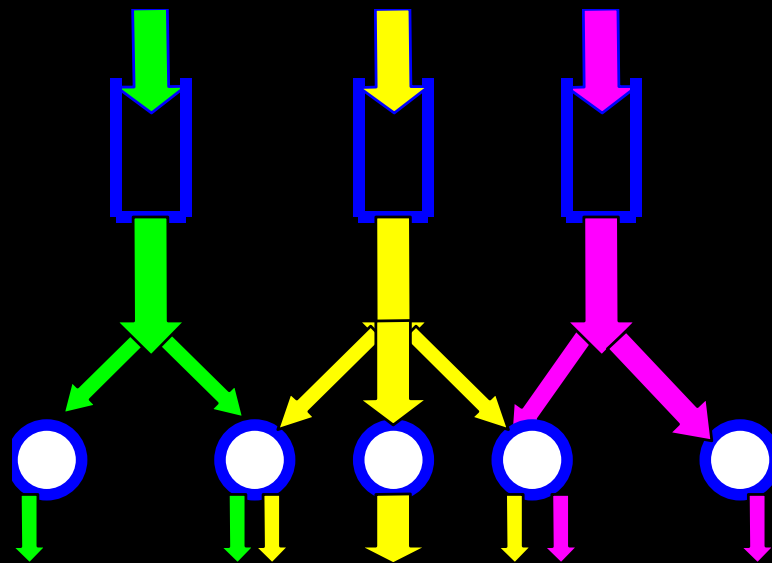
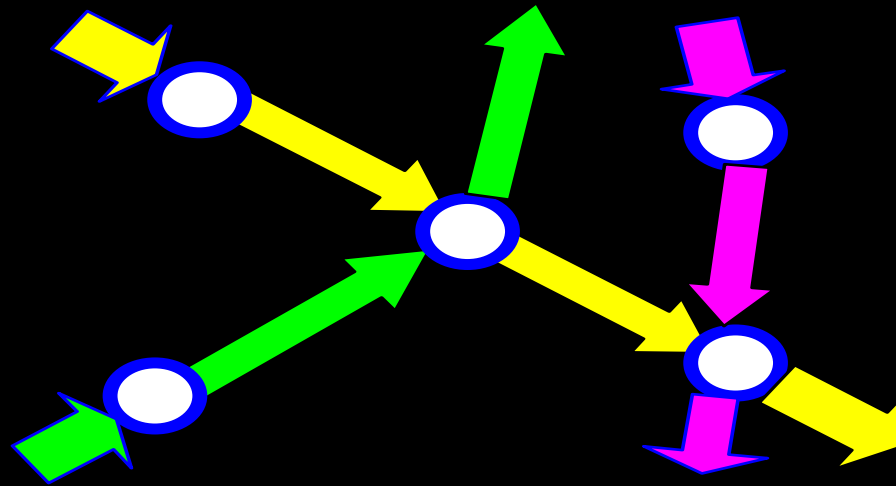


Link



Route

Simultaneous Resource Possession



Stochastic Processing Networks

■ APPLICATIONS

Complex manufacturing, telecommunications, computer systems, service networks

■ FEATURES

Multiclass, service discipline, alternate routing, complex feedback, heavily loaded

■ PERFORMANCE MEASURES

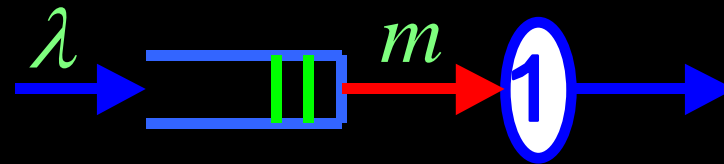
Queue length, workload and server idletime

QUESTIONS

- STABILITY
- PERFORMANCE ANALYSIS (when heavily loaded)
- CONTROL (involves performance analysis for "good" controls)

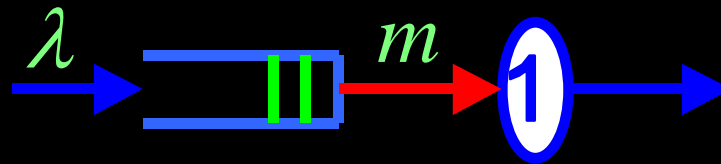
A SIMPLE EXAMPLE: SINGLE SERVER QUEUE

M/M/1 Queue



- Poisson arrivals at rate λ (independent of service times)
- i.i.d. exponential service times mean m
- FIFO order of service, infinite buffer

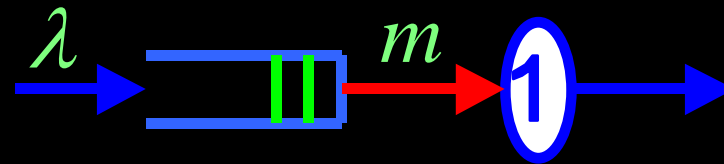
M/M/1 Queue



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- Traffic intensity $\rho = \lambda m$

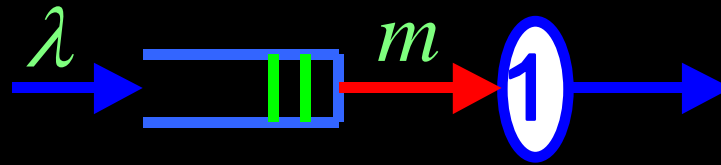
M/M/1 Queue



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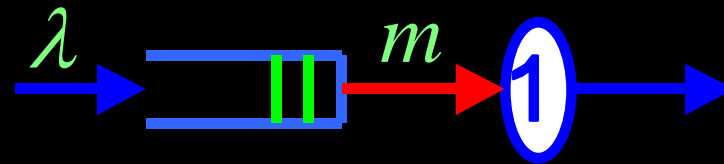
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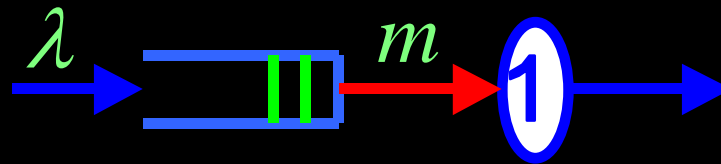
M/M/1 Queue



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- Stationary distribution $\pi_i = \rho^i (1 - \rho)$, $i = 0, 1, 2, \dots$
- Mean steady-state queue length $L = \rho / (1 - \rho)$

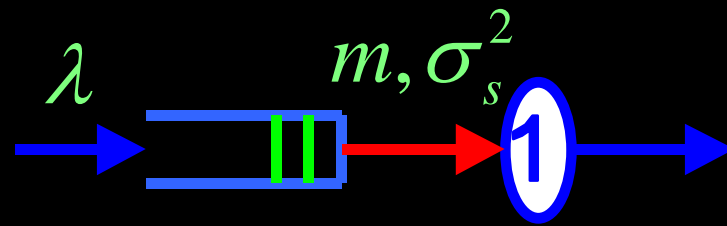
M/M/1 Queue



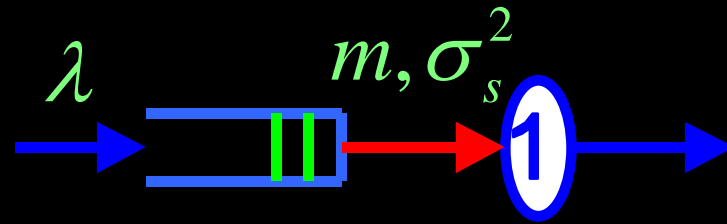
- Poisson arrivals at rate λ (independent of service times)
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- Mean steady-state queue length $L = \rho / (1 - \rho) = \lambda W$

M/GI/1 Queue



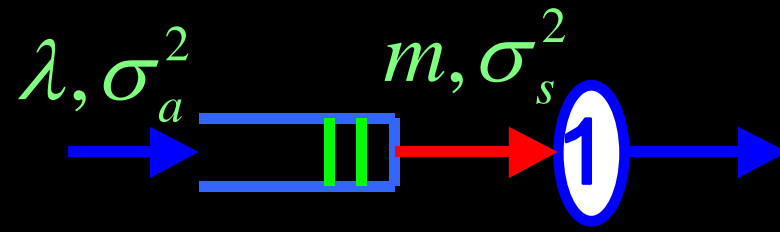
M/GI/1 Queue



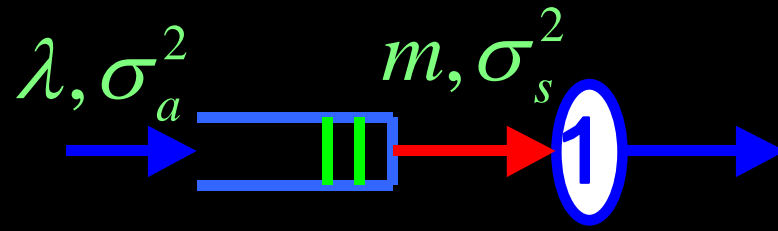
- Mean steady-state queue length

$$L = \rho + \frac{\rho^2 + \lambda^2 \sigma_s^2}{2(1 - \rho)} \quad (\text{Pollaczek-Khintchine})$$

GI/GI/1 Queue (+mild reg. assumptions)



GI/GI/1 Queue (+mild reg. assumptions)

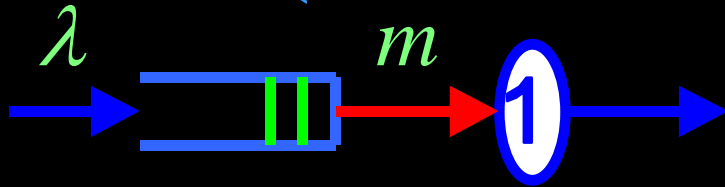


$$(1 - \rho)L \approx \frac{\lambda^2 (\sigma_a^2 + \sigma_s^2)}{2} \quad \text{for } \rho \approx 1$$

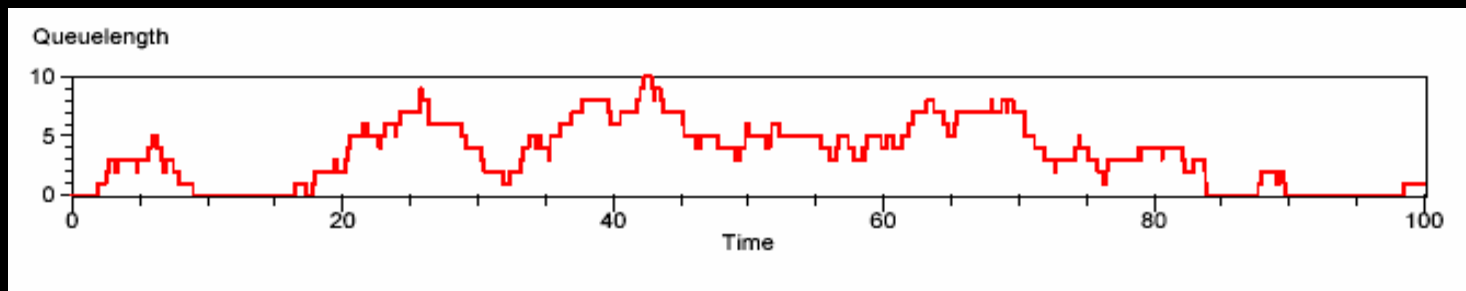
(Smith '53, Kingman, '61)

M/M/1 Queue

(Simulation of Dynamics)

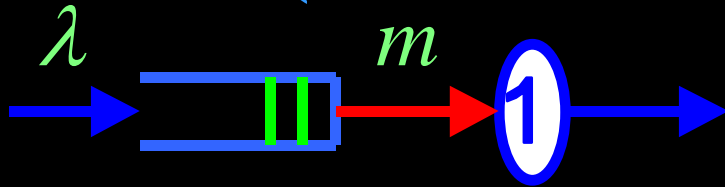


$$\rho = \lambda = 0.9524$$

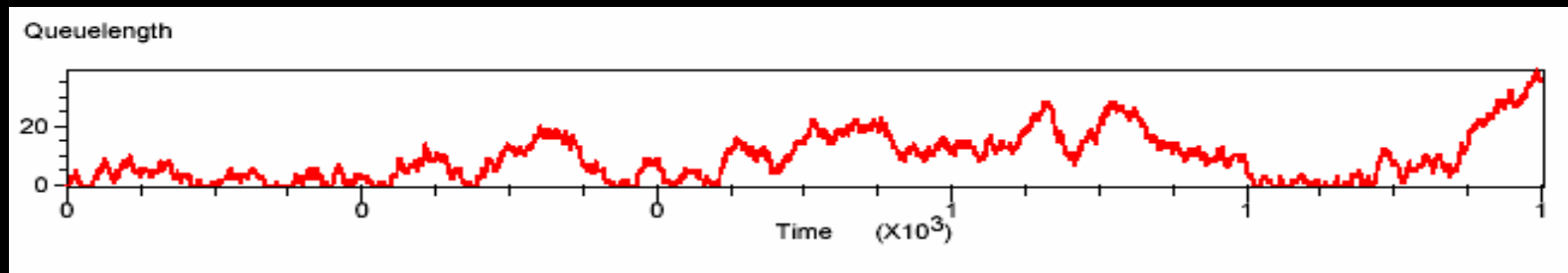
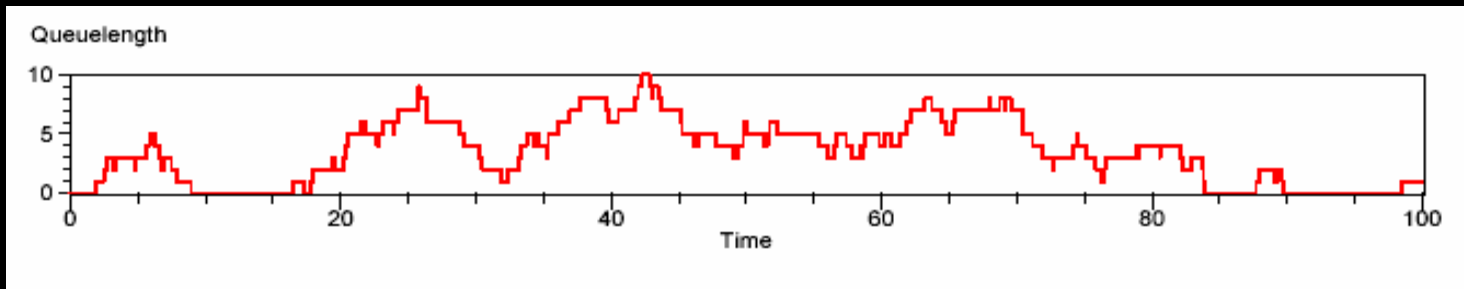


M/M/1 Queue

(Simulation of Dynamics)

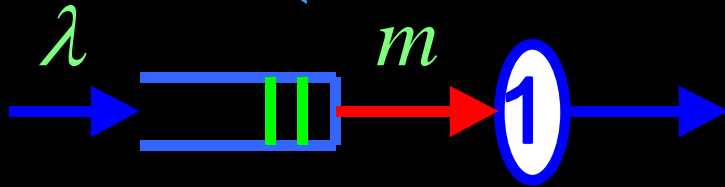


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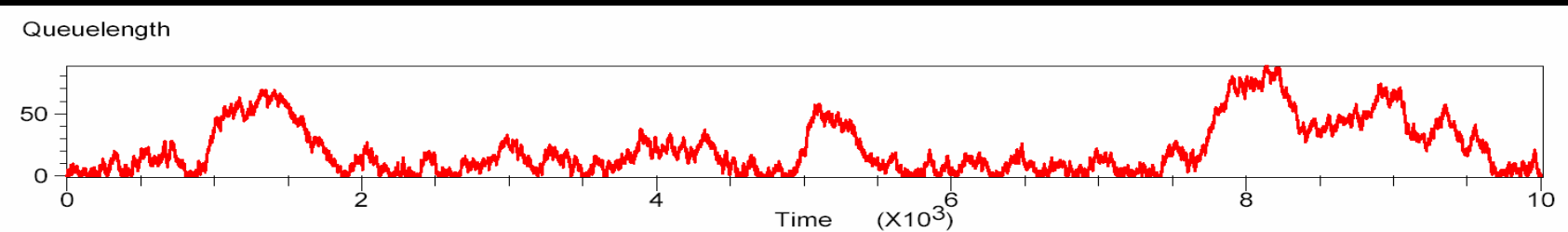
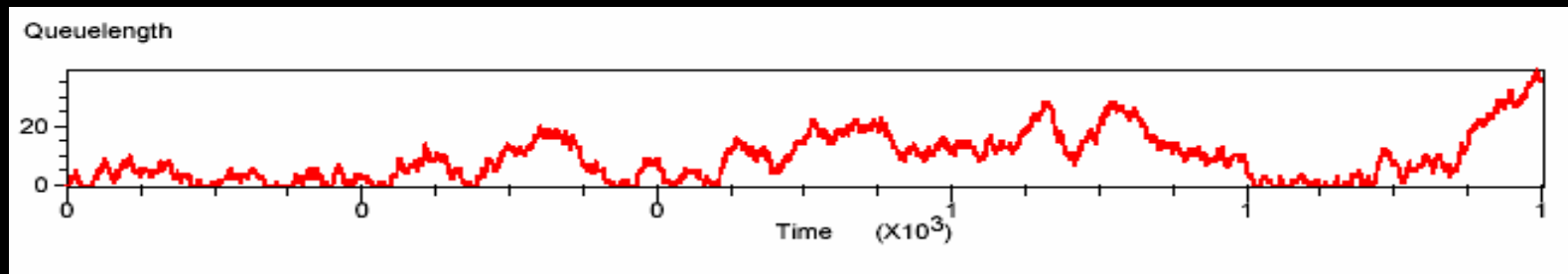
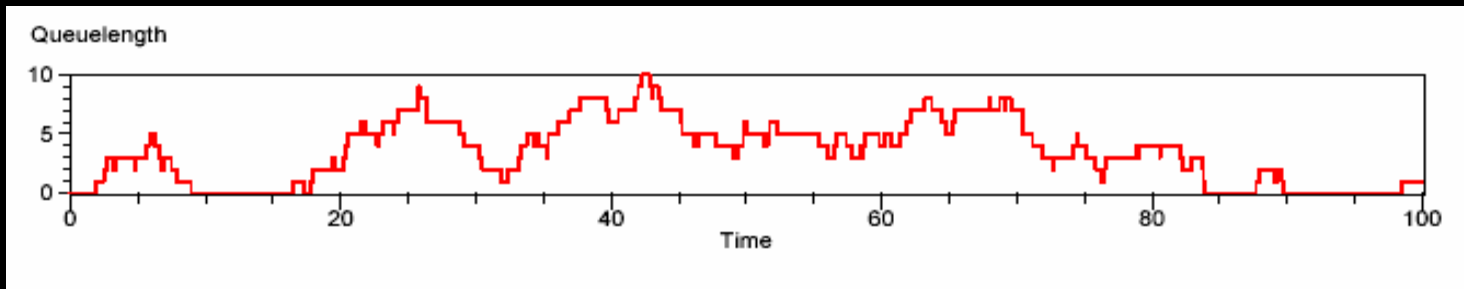


M/M/1 Queue

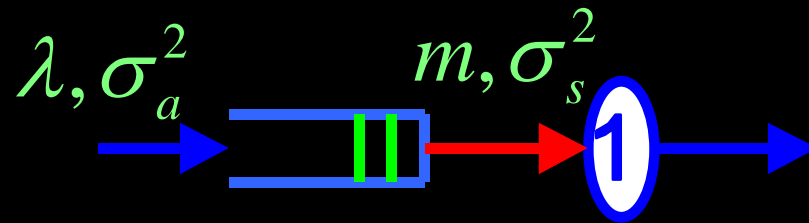
(Simulation of Dynamics)



$$\rho = \lambda = 0.9524$$



GI/GI/1 Queue (Dynamics)



$Q(t)$ = queue length at time t

Start system empty (for simplicity)

Theorem (A. Borovkov '67, Iglehart-Whitt '70): For $\rho \approx 1$,

$$(1 - \rho)Q(\cdot / (1 - \rho)^2) \approx Q^*(\cdot) \quad \text{where } Q^*(\cdot)$$

is a one-dimensional reflecting Brownian motion

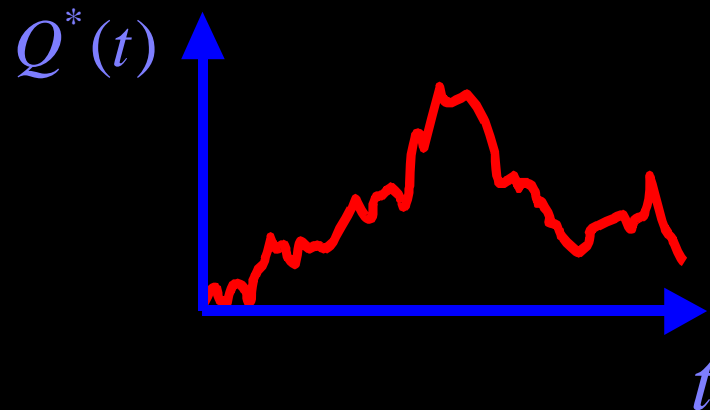
with drift $-m^{-1}$ and variance parameter $\lambda^3 \sigma_a^2 + m^{-3} \sigma_s^2$

One-dimensional Reflecting Brownian Motion

$$Q^*(t) = X^*(t) + Y^*(t)$$

$$Y^*(t) = \sup\{-X^*(s) : 0 \leq s \leq t\}$$

X^* = Brownian motion



APPROXIMATE DYNAMIC MODELS

- Most SPNs cannot be analyzed exactly
- Consider approximate models (valid under some scaling limit, e.g., heavily loaded, many sources, many servers, large networks)
- Two main classes of approximate models:
 - Fluid models (functional law of large numbers)
 - Diffusion models (functional central limit theorem)

ANSWERS

(OPEN MULTICLASS HL QUEUEING NETWORKS)

Last 15 years: development of a theory for establishing stability and heavy traffic diffusion approximations for open multiclass queueing networks with non-idling head-of-the-line (HL) service disciplines.

Head-of-the-line: service allocated to a buffer goes to the job at the head-of-the-line (jobs within buffers are in FIFO order).

PERSPECTIVE

MQN

SPN

HL

Sufficient conditions for
stability and diffusion
approximations

e.g., parallel server system,
packet switch

Non-
HL

e.g., LIFO, Processor Sharing
(single station,
PS: network stability)

e.g., Internet congestion
control / bandwidth sharing
model

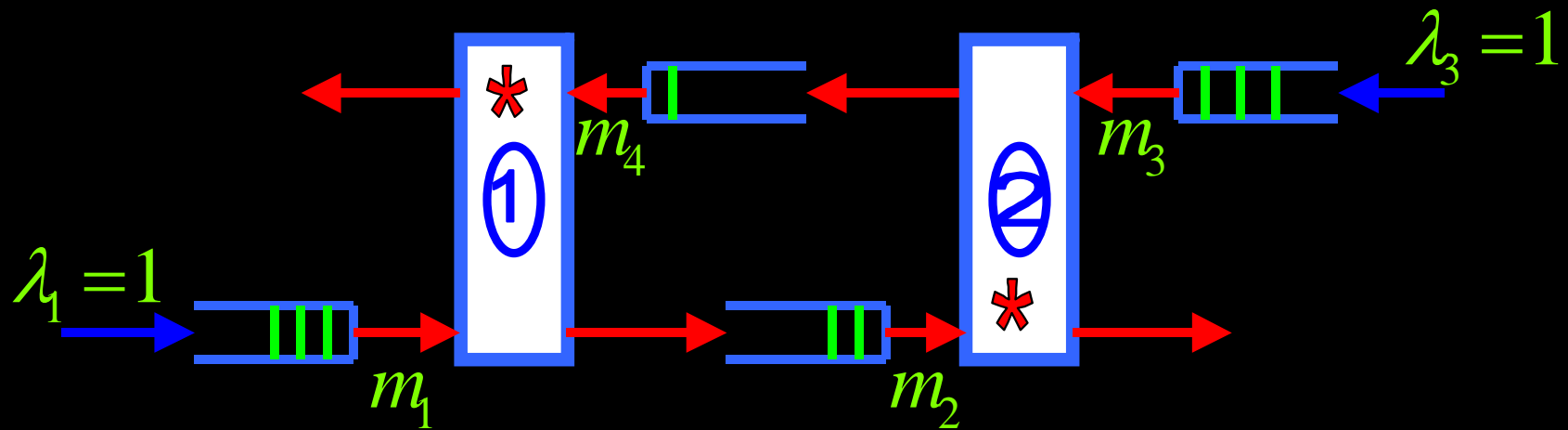
MOTIVATING EXAMPLES

Stability

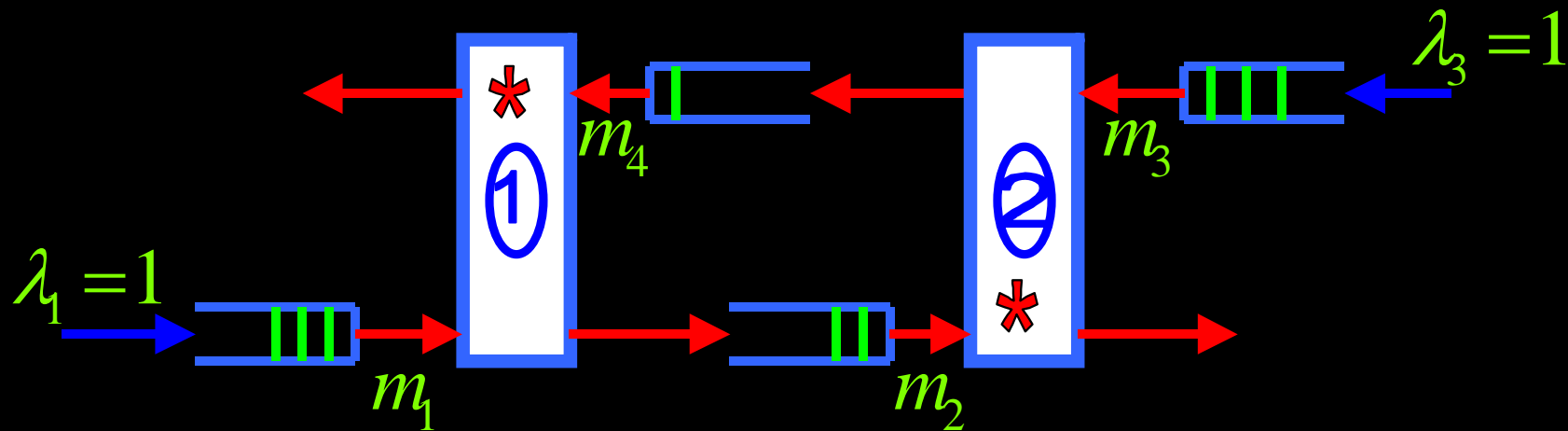
Performance

Control

Two-Station Priority Queueing Network (Rybko-Stolyar '92)

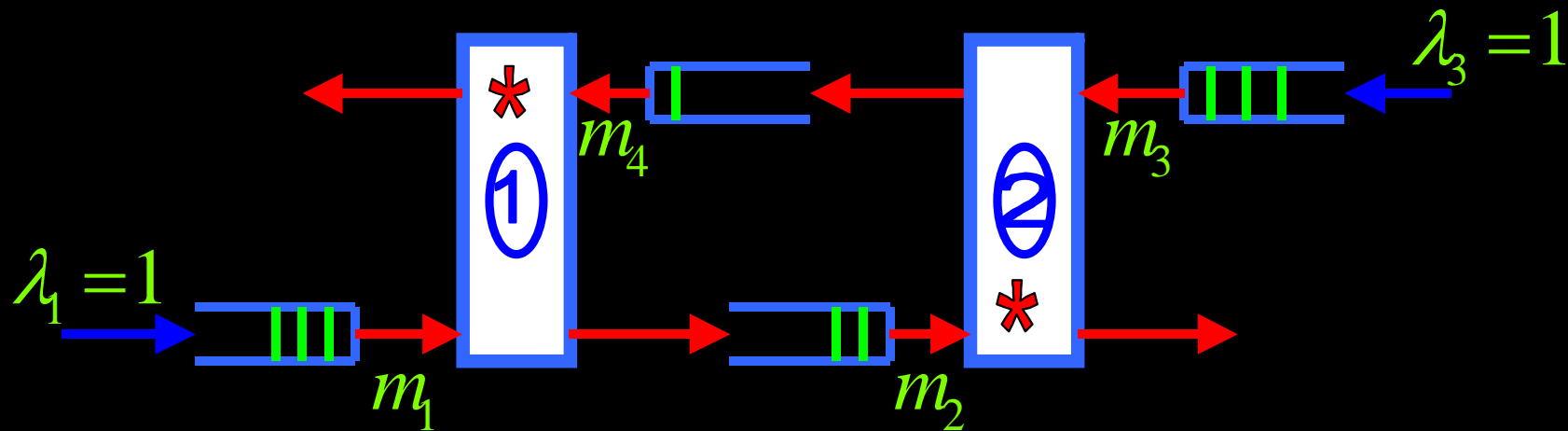


Two-Station Priority Queueing Network (Rybko-Stolyar '92)



- Poisson arrivals at rate 1 to buffers 1 and 3
- Exponential service times: m_i mean rate of service for buffer i
- Preemptive resume priority: * denotes high priority classes

Two-Station Priority Queueing Network (Rybko-Stolyar '92)

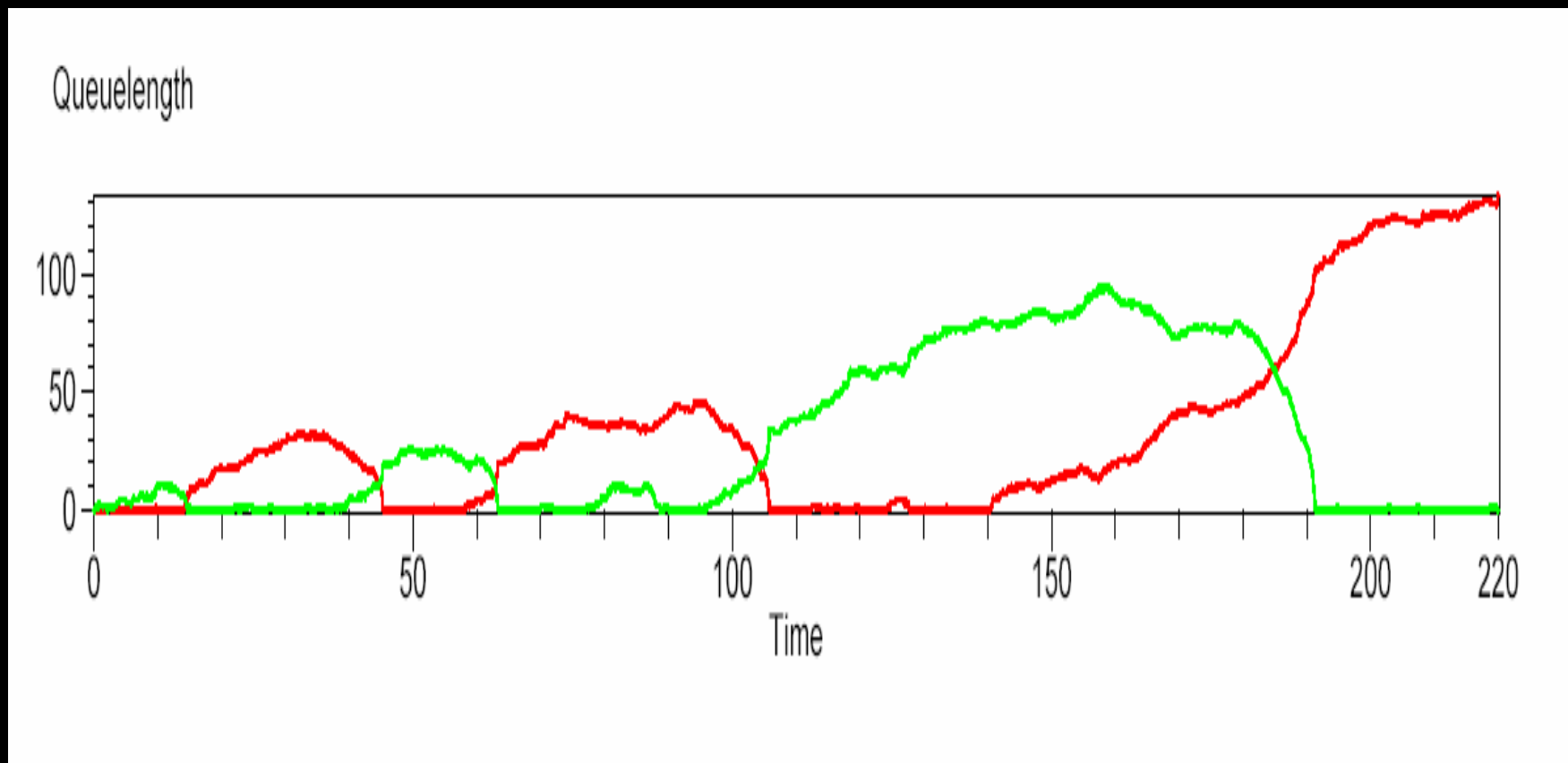


- Poisson arrivals at rate 1 to buffers 1 and 3
- Exponential service times: m_i mean rate of service for buffer i
- Preemptive resume priority: * denotes high priority classes
- Simulation: $m_1 = m_3 = 0.33$, $m_2 = m_4 = 0.66$
- Traffic intensities: $\rho_1 = m_1 + m_4 = 0.99$ $\rho_2 = m_2 + m_3 = 0.99$

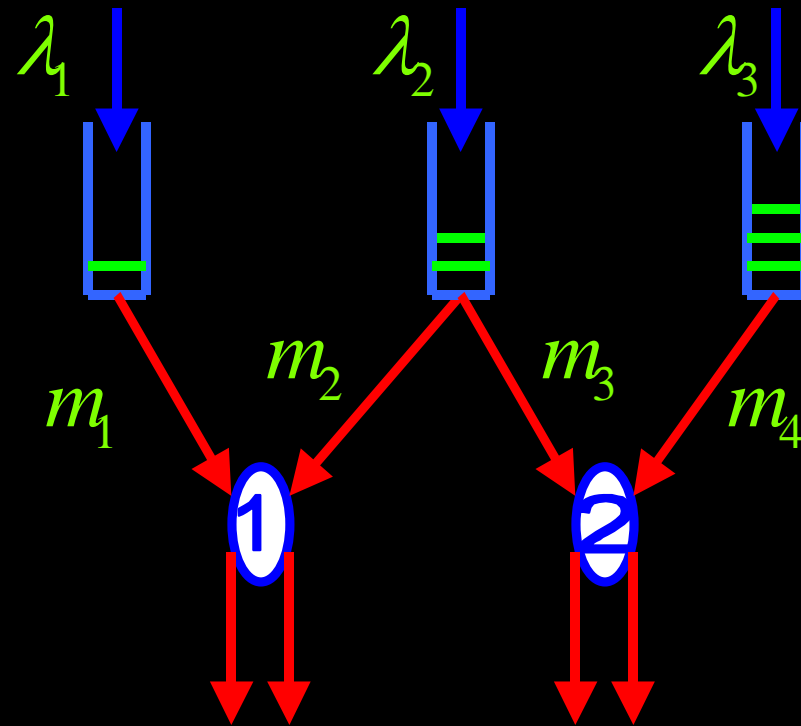
Two-Station Priority Queueing Network (Rybko-Stolyar '92)

--- Server 1 (sum of queues 1 & 4)

--- Server 2 (sum of queues 2 & 3)



Parallel Server System



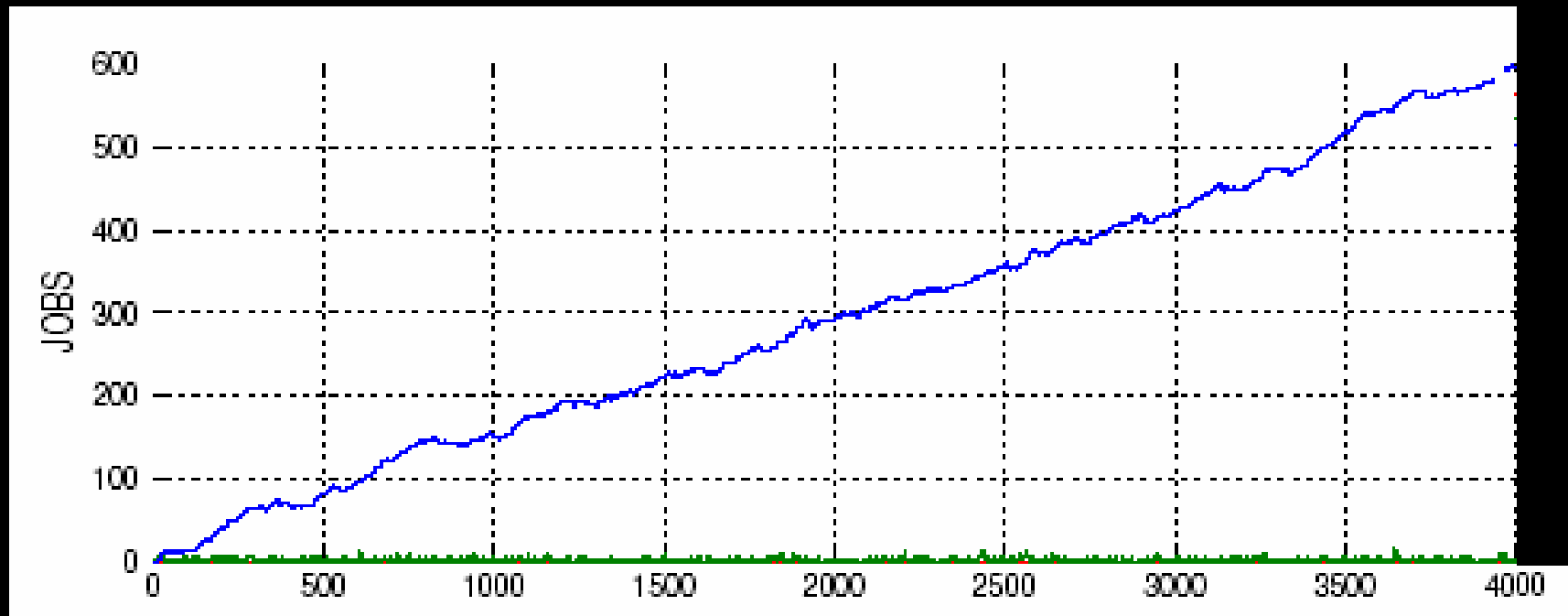
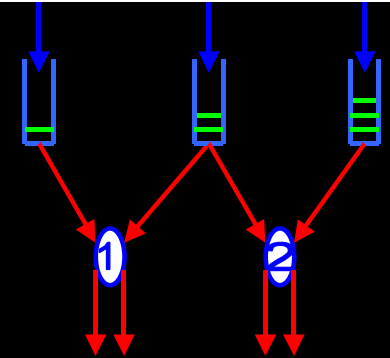
$$\lambda_1 = 0.05, \lambda_2 = 1.2, \lambda_3 = 0.35$$

$$m_1 = 0.5, m_2 = 1, m_3 = 1, m_4 = 2$$

Parallel Server System

Simulation with static priority discipline:

server 1 gives priority to buffer 1, server 2 gives priority to buffer 2

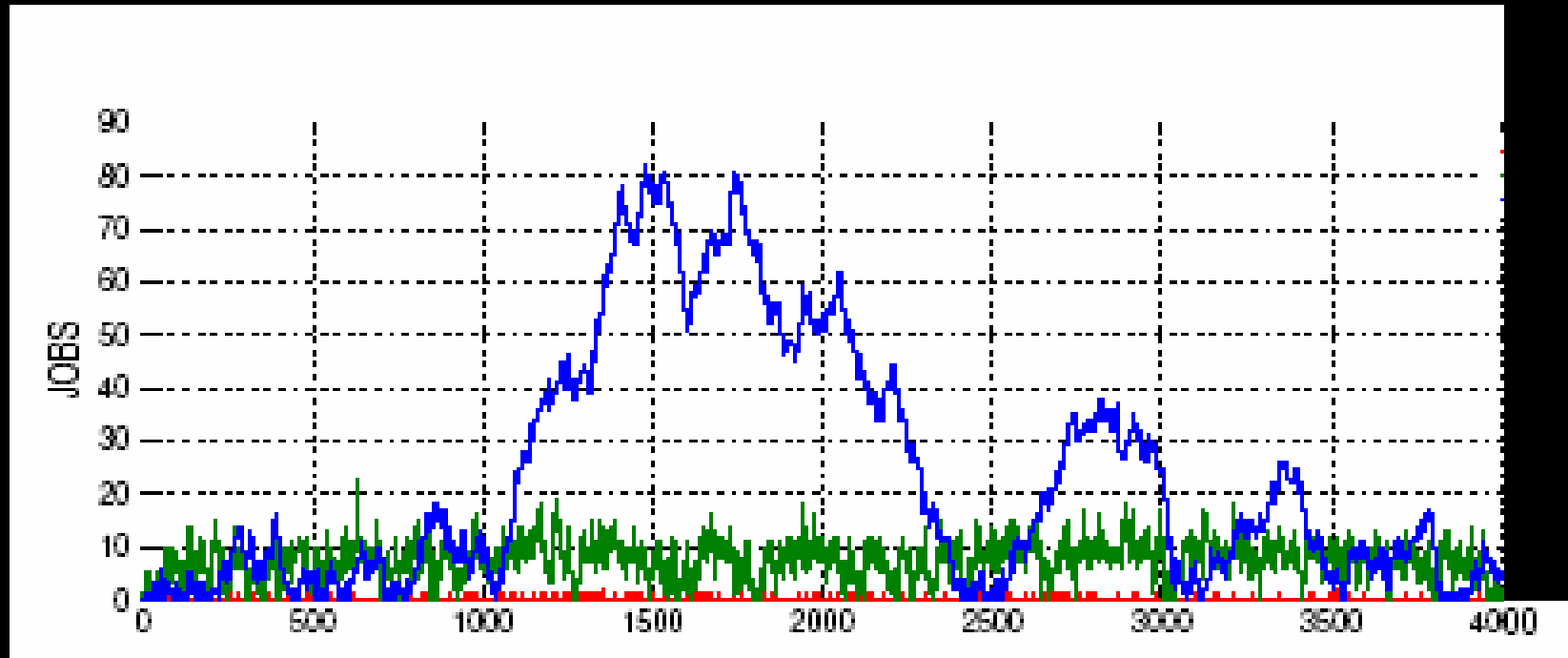
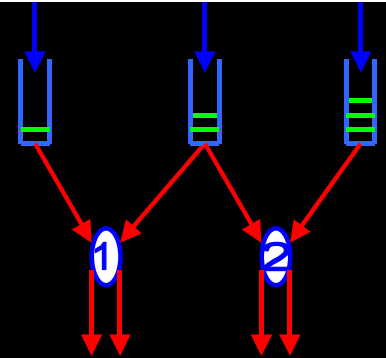


Queue lengths for **buffer 1** ---, **buffer 2** ---, **buffer 3** --- versus time

Parallel Server System

Simulation with dynamic priority discipline:

server 1 gives priority to buffer 1, server 2 gives priority to buffer 2, except when queue 2 goes below **threshold** of size 10



Queue lengths for **buffer 1** ---, **buffer 2** ---, **buffer 3** --- versus time

MAIN TOPICS FOR REMAINING LECTURES

- Open Multiclass HL Queueing Networks: Stability and Performance
- Control of Stochastic Processing Networks: Some Theory and Examples

