

#### Covariance

## Let s<t. Then $E[B_sB_t]$

# So, in general, E[BsB]



Lemma: If (Xt)trT: (S,J,P) > 12 are vandom variables, then  $\chi(t,s) = \chi(s,t) = Cov[\chi_s,\chi_t]$  is positive-definite. Pf. Fix  $\Lambda \subseteq T$  finite, and note that for any  $Z: \Lambda \to \mathbb{R}$ ,  $\sum_{s,t\in T} \chi(s,t) Z(s) Z(t)$ 

So, we now know that the function  $\chi_{(s,t)} = snt$  is positive definite.

Eq.  $\chi(s,t) = s \wedge t - st$ ,  $o \leq s, t \leq 1$ 



### Gaussian Processes

Recall [Lec 26.]] a random vector X & Rd is called (jointly) Gaussian if the characteristic function has the form  $\mathcal{C}_{\hat{X}}(\hat{z}) = \mathbb{E}[e^{i\hat{z}\cdot\hat{X}}] = e^{-\frac{1}{2}||A^T\hat{z}||^2}$ 

for some A & Mdxd. Equivalently, by the Cramér-Hold device, X is Gaussian iff Z-X is a normal random variable YZERd

It is not sufficient just to check that the components of X are normally distributed.

Eq.  $X \stackrel{d}{=} \mathcal{N}(0,1), R \stackrel{d}{=} \frac{1}{2}S_1 + \frac{1}{2}S_{-1}, X, R$  independent. Y = RX

But (X,Y) is not jointly Gaussian. [Hw]



Note: if TIRd > Rd is an invertible linear transformation, and if I=T(X) is a Gaussian random vector, then so is X

- In particular: permuting the entries preserves joint Gaussianness. Def: A stochastic process (Xt)ter: (2,F,P) -> R is called a Gaussian Process if, for any finite collection of times ti,-, the T, (Xt,-, Xtn) is a Gointhy) Gaussian vandom vector.
- Prop. Brownian motion is a Gaussian process.
- Pf. Let  $Ost_1 < t_2 < \cdots < t_n$ .
  - Let  $T(x_1, x_2, ..., x_n) = (x_1, x_2 x_1, x_3 x_2, ..., x_n x_{n-1})$
  - $T(B_{t_{1},--,}B_{t_{n}}) = (B_{t_{1}}, B_{t_{2}}-B_{t_{1}}, --, B_{t_{n}}-B_{t_{n-1}})$



Theorem: Let c: T > IR be any function, and let X: TXT > IR be posselfinite. Then there exists a Ganssian process (Xt) ter= (2,F,P) -> IR with  $\mathbb{E}[X_{t}]=c(t)$  and  $Cov(X_{s}, X_{t}) = X(s, t)$   $\forall s, t \in T$ . Moreover, any two Gaussian processes with mean c and Guariance Q have the same finite - dimensional distributions.

- Pf. Existence is an exercise in Kelmogorov's Extension theorem; [Driver, Prop 31.6]. ter f.d. uniqueness: if X is a Gaussian vector,
  - $(e_{\hat{X}}(\hat{z})) = e^{-\frac{1}{2}\hat{z}\cdot\hat{C}\hat{z}}$  for a positive semi-definite matrix C



Cor: If (X+) to E0,00) is a continuous Gaussian process with E[X+]=0, E[XsX+]= srt +s,t=0 then X. is a Brownian motion. Pf. By the uniqueness result of the last theorem, X. and B. have the same finite-dimensional distributions.

