

## Covariance



So, in general, E[BsBt] = srt Cu(Bs,Bz) bk EEBs1=0 ts>0

Note: if  $\{X_t\}_{t\in T}$  is any collection of random variables on a given probability space, the function  $\chi: T \times T \rightarrow \mathbb{R}$ ,  $\chi(s,t) = Gv[X_s, \chi_t]$ 

has a positivity property. semi

Def: A function X: TXT > IR is positive definite

iff for any finite subset N= {ti,-,tn} CT, the matrix

Mij = X(ti,ti) is positive semidefinite. I. M. M. & Z. MZ = O VZCIRN (VZ: A->IR.





## Gaussian Processes

Recall [Lec 26.]] a random vector X & IRd is called (jointly) Gaussian if the characteristic function has the form  $C_{\hat{X}}(\hat{z}) = E[e^{i\hat{z}\cdot\hat{X}}] = e^{-\frac{1}{2}||A^T\hat{z}||^2} = e^{-\frac{1}{2}\hat{z}\cdot C\hat{z}}$ 

 $\varphi_{\mathbf{X}}(t) = e^{-\frac{1}{2}s} \cdot c_{\mathbf{x}} t_{\mathbf{y}} \cdot \mathbf{x}$ for some AGMdxd. Equivalently, by the Cramér-Hold device, X is Gaussian iff z.X is a normal random variable Vzerd. Eg. Z= ex > Xx are rornally distributed, ker, og, It is not sufficient just to check that the components of X are normally distributed.

Eq.  $X \stackrel{d}{=} N(0,1), R \stackrel{q}{=} \frac{1}{2}S_1 + \frac{1}{2}S_{-1}, X, R$  independent.  $Y = RX \stackrel{d}{=} N(0,1)$ ,  $X \stackrel{d}{=} -X$ 

But (XX) is not jointly Granssian. [HW]





Note: if TIRd > Rd is an invertible linear transformation, and if I=T(X) is a Gaussian random vector, then so is X.  $z \cdot \overline{X} = \overline{z} \cdot \overline{T}'(\overline{Y}) = (\overline{T}')^T \overline{z} \cdot \overline{Y}$  is normally distributed. In particular: permuting the entries preserves joint Graussianness.

Def: A stochastic process (Xt) ter: (2,F,P) -> R is called a Gaussian Process if, for any finite collection of times ti,-, the T, (Xti,-, Xth) is a Gointhy) Gaussian varelon vector

Propi Brownian motion is a Gaussian process.

Pf. Let Ost, 2t2 <--- < tn. (suff, 2.1)

 $Let T(x_1, x_2, ..., x_n) = (x_1, x_2 - x_1, x_3 - x_2, ..., x_n - x_{n-1})$  $inverse: T(y_1, -, y_n) = (y_1, y_1 + y_2, y_1 + y_2, -, y_1 + - + y_n)$ 

 $= \mathcal{N}(\mathcal{Q}, \begin{pmatrix} t_1 & t_2 & t_2 \\ 0 & -t_1 & -t_2 \end{pmatrix}) ///$ 

 $T(B_{t_{1},--,}B_{t_{n}}) = (B_{t_{1}}-B_{o}, B_{t_{2}}-B_{t_{1}}, --, B_{t_{n}}-B_{t_{n-1}})$ 





Cor: If (X) de EO,00) is a continuous Graussian process with E[X]=0, E[XsX]= srt Hs,t=0 then X is a Brewnian motion. Pf. By the uniqueness result of the last theorem, X and B. have the same finite-dimensional distributions.

