Time Homogeneity

Eq. Poisson process Nt $q_{s,t}(n,B) = \mathbb{E}[I_B(n+N_t-N_s)]$

Eg. (pre-) Brownian motion Bt $q_{s,t}(z,B) = E[J_B(z+B_t-B_s)]$

These transition kernels qs, t depend on s, t only through t-s.

Def. A collection Qs, is setter of Markov transition operators is called time homogeneous if

 $Q_{s,t} = Q_{o,t-s}$ $\forall s \leq t \in T$.

In this case, the Chapman-Kolmogorov equations become $Q_{SQ_{t}} = Q_{S+t}$, $Q_{o} = Id$.



is called a 1-parameter semigroup.

- If (Xt)ter is a Markov process with time homogeneous transition operators,
- it is called a time homogeneous Markov process.







For any time homogeneous Markov process, all f.d. distributions are determined by vo and the transition semigroup (Qt)tet.

Thinking of the process as a measure on path space, we fix the transition semigroup and consider the family P^{ν} of processes with different starting distributions ν .

Notation: We let X = (XDzer denote a whole family of Markov processes with given transition semigrand (Qt)tet - For FEB(ST, BOT),

 $E^{v}(F(X)) = expected value of F(the process with <math>X_{e} = v)$. In the case $V = S_{x}$, we write

Theorem: If X is a time homogeneous Marker process for FEB(ST, BOT), 21-> E²[F(X)] is measurable. Moreover, for t=0, VoeProb(SB), $\mathbb{E}^{0}[F(X_{t+-})|F_{t}] = \mathbb{E}^{0}[F(X_{t+-})|X_{t}] = \mathbb{E}^{X_{t}}[F(X)]$



Theorem: If X. is a time homogeneous Markov process, FEB(SOT)



- Pf. $F(X_{t+}) \in B(\Omega, \mathcal{F}_{\geq t})$. We showed in [lecture 36.1] that if Y then
- For the remainder of the proof, we take F of the form
- $F(w) = f(w(t_0))f_1(w(t_1)) f_n(w(t_n))$
- Prove 1,2 for such F; then extend by Dynkin
- $1 \mathbb{E}^{\alpha}[F(X_{-})] = \mathbb{E}^{\alpha}[f_{0}(X_{t_{0}}) f_{n}(X_{t_{n}})]$



2. Want to show $E^{v}[F(X_{t+-})|X_t] = E^{X_t}[F(X)]$

 $F(X_{t+-}) = f_o(X_t)f_i(X_{t+t_i}) - - f_n(X_{t+t_n}).$

 $: \forall h \in B(S, B),$ $E^{v}[h(X_{t})F(X_{t+1})] = E^{v}[h(X_{t})f_{n}(X_{t})f_{n}(X_{t+1}) - - f_{n}(X_{t+1})]$

Now $V_o(dx)\int q_t(x,dy) = V_t(dx)$

