Markov Processes

- Let (R,F, (Ftiter, P) be a filtered probability space.
- Let Xt: (SZT) > (SB) be an adapted process, satisfying the Markov property.
 - E[f(XE)]Fs] = E[f(XE)|Xs] a.s. V s<t in T, feB(S,B).
- Let's suppose (S,B) is a regular Borel space. Then there exists a regular conditional distribution 9s,t of Xt IXs:
- What can we say about these transition operators?
- Suppose r<s<tin T. Then
- $Q_{r,t}f(X_r) = \mathbb{E}[f(X_t)|X_r]$

 $Te_{-}\int Qr_{,t}f(x)\mu_{x_{r}}(dx) =$

Thus Egyberret satisfy

9r,t(x,B) = J9r,s(x,dy)9s,t(y,B) for Mx,-9.2. X.



1-2 are the Chapman-Kelmagorev equations.

I This could be problematic.



Let's focus on discrete time, for a moment, wlog T=N. (Xn)neN, {Qm,n=csmsncco}

The Chapman-Kelmogorov equations imply that

. In this case it suffices to know the 1-step transition operators (Qm, m+1-meNf.

What if the state space is also discrete? I.e. S is countable.

 $\frac{1}{2} - \frac{9}{10}m_{H}(x,B) = \sum_{\substack{y \in B}} \frac{9}{10}m_{H}(x,y)$

 $Qm_{n} =$

: C-K Says

Finite - Dimensional Distributions

- Let (Xt)bet be a Markov process with transition kernels
- Fix any times to < b, < -- < tn. let vo = Law (Xt).
- Prop: The law of (Xt, Xt, ..., Xtn) is
 - Law (Xto, Xt, ..., Xtn) (dxdx, ... dxn) = Vo(dxo) 9to, ti (xo, dxi) 9t, t2(x, dx2) ... 9th, tn (xn, dxn)



{9s,tJs≤€-