

Markov Processes

Let $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \in T}, \mathbb{P})$ be a filtered probability space.

Let $X_t: (\Omega, \mathcal{F}_t) \rightarrow (S, \mathcal{B})$ be an adapted process, satisfying the Markov property.

$$\mathbb{E}[f(X_t) | \mathcal{F}_s] = \mathbb{E}[f(X_t) | X_s] \quad \text{a.s.} \quad \forall s < t \text{ in } T, f \in \mathcal{B}(S, \mathcal{B}).$$

Let's suppose (S, \mathcal{B}) is a regular Borel space.

Then there exists a regular conditional distribution $q_{s,t}$ of $X_t | X_s$:

$$\mathbb{E}[f(X_t) | X_s] = \int_S f(y) q_{s,t}(X_s, dy) = Q_{s,t} f(X_s)$$

What can we say about these transition operators?

Suppose $r < s < t$ in T . Then $\sigma(X_r) \subseteq \mathcal{F}_r \subseteq \mathcal{F}_s$

$$\begin{aligned} Q_{r,t} f(X_r) &= \mathbb{E}[f(X_t) | X_r] = \mathbb{E}[\mathbb{E}_{\mathcal{F}_s}[f(X_t)] | X_r] \\ &= \mathbb{E}[Q_{s,t} f(X_s) | X_r] = Q_{r,s}(Q_{s,t} f)(X_r) \end{aligned}$$

$$\text{I.e.} \quad \int Q_{r,t} f(x) \mu_{X_r}(dx) = \int (Q_{r,s} Q_{s,t} f)(x) \mu_{X_r}(dx) \quad \forall f$$

$$\int f d \overset{||}{\mu_{X_r} \otimes q_{r,t}} = \int f d \overset{||}{\mu_{X_r} \otimes (q_{r,s} \otimes q_{s,t})}.$$

Thus $\{q_{r,t}\}_{r \leq t}$ satisfy

$$q_{r,t}(x, B) = \int q_{r,s}(x, dy) q_{s,t}(y, B) \text{ for } \mu_{x_r}\text{-a.e. } x.$$

$$\text{I.e. } \forall f \in \mathcal{B}(\mathcal{S}, \mathcal{B}), \quad Q_{r,t}f = Q_{r,s}Q_{s,t}f \text{ } [\mu_{x_r}\text{-a.s.}]$$

To avoid possible measure-theoretic pitfalls, we strengthen this to hold $\forall x$.

⌈ This could be problematic, what if $\mu_{x_r} \perp \mu_{x_s}$ for $s \neq r$?

Def: A collection of probability kernels $\{q_{s,t}\}_{s \leq t}$ (operators $\{Q_{s,t}\}_{s \leq t}$)

Markov transition kernels (**operators**) if

$$1. \quad q_{s,s}(x, \cdot) = \delta_x \quad (Q_{s,s} = \text{Id}) \quad \forall s \in T, x \in S.$$

$$2. \quad Q_{r,t} = Q_{r,s}Q_{s,t} \quad \forall r \leq s \leq t$$

$$\text{I.e. } q_{r,t}(x, B) = \int q_{r,s}(x, dy) q_{s,t}(y, B) \text{ for all } x \in S.$$

1-2 are the **Chapman-Kolmogorov equations**.

Def: Given $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \in T}, \mathbb{P})$ and (S, \mathcal{B}) , an adapted stochastic process $X_t: \Omega \rightarrow S$ is a **Markov process** if it **satisfies the Markov property**, and there exist Markov transition operators $\{Q_{s,t}\}_{s \leq t}$

$$\text{s.t. } \mathbb{E}[f(X_t) | X_s] = Q_{s,t}(X_s) \quad \forall s \leq t \text{ in } T, f \in \mathcal{B}(S, \mathcal{B}).$$

We've seen that the Markov property implies (a.s. form) the Chapman-Kolmogorov equations. The converse is **false**. \leftarrow subtle.

Def: A process $(X_t)_{t \in T}$ has **independent increments**

if, for all $t_0 < t_1 < \dots < t_n$ in T ,

$$X_{t_1} - X_{t_0}, X_{t_2} - X_{t_1}, \dots, X_{t_n} - X_{t_{n-1}}$$

are independent. Eg. random walks, Poisson process.

Prop: An independent increment process X is a Markov

process (wrt $\{\mathcal{F}_t^X\}_{t \in T}$), and $X_t - X_s$ is independent from \mathcal{F}_s

$\forall s < t$. The transition kernels are

$$q_{s,t}(x, B) = \mathbb{P}[\mathbb{1}_B(x + X_t - X_s)]$$

Let's focus on discrete time, for a moment, wlog $T=N$.

$$(X_n)_{n \in \mathbb{N}}, \{Q_{m,n} = 0 \leq m \leq n < \infty\}$$

The Chapman-Kelmgorov equations imply that

$$Q_{m,n} = Q_{m,m+1} Q_{m+1,m+2} \dots Q_{n-1,n}.$$

\therefore In this case it suffices to know the 1-step transition operators $\{Q_{m,m+1} = m \in \mathbb{N}\}$.

What if the state space is also discrete? I.e. S is countable.

$$\therefore q_{m,m+1}(x, B) = \sum_{y \in B} q_{m,m+1}(x, y)$$

"path integrals"

↑ This is a RCD of X_{m+1}/X_m

$$q_{m,m+1}(x, y) = \begin{cases} P(X_{m+1}=y | X_m=x) \\ 0 \text{ if } P(X_m=x) = 0. \end{cases}$$

\therefore C-K says

$$q_{m,n}(x, y) = \sum_{x_{m+1}, \dots, x_{n-1} \in S} q_{m,m+1}(x, x_{m+1}) q_{m+1,m+2}(x_{m+1}, x_{m+2}) \dots q_{n-1,n}(x_{n-1}, y)$$

Finite-Dimensional Distributions

Let $(X_t)_{t \in T}$ be a Markov process with transition kernels $\{q_{s,t}\}_{s \leq t}$.

Fix any times $t_0 < t_1 < \dots < t_n$. Let $\nu_0 = \text{Law}(X_{t_0})$.

Prop: The law of $(X_{t_0}, X_{t_1}, \dots, X_{t_n})$ is

$$\text{Law}(X_{t_0}, X_{t_1}, \dots, X_{t_n})(dx_0 dx_1 \dots dx_n) = \nu_0(dx_0) q_{t_0, t_1}(x_0, dx_1) q_{t_1, t_2}(x_1, dx_2) \dots q_{t_{n-1}, t_n}(x_{n-1}, dx_n)$$

$$\mathbb{E}[f_0(X_{t_0}) f_1(X_{t_1}) \dots f_n(X_{t_n})] = \mathbb{E}_{\nu_0}[f_0 Q_{t_0, t_1}(f_1 Q_{t_1, t_2}(\dots (f_{n-1} Q_{t_{n-1}, t_n} f_n) \dots))].$$

Pf. By Dynkin, suffices to prove

Now proceed by induction. (base case: $\nu_0 = \text{Law}(X_{t_0})$)

$$\mathbb{E}[\mathbb{E}[f_0(X_{t_0}) f_1(X_{t_1}) \dots f_n(X_{t_n}) f_{n+1}(X_{t_{n+1}}) | \mathcal{F}_{t_n}]] = \mathbb{E}[f_0(X_{t_0}) \dots f_n(X_{t_n}) \mathbb{E}[f_{n+1}(X_{t_{n+1}}) | \mathcal{F}_{t_n}]] \quad [g_n = f_n \cdot Q_{t_n, t_{n+1}} f_{n+1}]$$

$$\mathbb{E}[f_{n+1}(X_{t_{n+1}}) | X_{t_n}] = Q_{t_n, t_{n+1}} f_{n+1}(X_{t_n})$$

$$= \mathbb{E}[f_0(X_{t_0}) \dots f_{n-1}(X_{t_{n-1}}) g_n(X_{t_n})]$$

$$= \mathbb{E}_{\nu_0}[f_0 Q_{t_0, t_1}(f_1 Q_{t_1, t_2}(\dots (f_{n-1} Q_{t_{n-1}, t_n} g_n) \dots))]$$

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