

In [Lectures 33.1, 33.2, 34.1] we introduced probability kernels Q , regular conditional distributions, and associated integral operators L .

We're going to change some notation and terminology for these now (sorry!) to avoid some later confusion.

Summary: $Q \rightarrow q$ probability kernel
 $L \rightarrow \mathcal{Q}$ Markov (transition) ~~generator~~ operator.

A **probability kernel** over $(S_1, \mathcal{B}_1), (S_2, \mathcal{B}_2)$ is a function

$$q: S_1 \times \mathcal{B}_2 \rightarrow [0, 1]$$

s.t.

$$q(x, \cdot) \in \text{Prob}(S_2, \mathcal{B}_2) \quad \forall x \in S_1$$

&

$$q(\cdot, B) \text{ is } \mathcal{B}_1/\mathcal{B}(\mathbb{R})\text{-measurable } \forall B \in \mathcal{B}_2$$

Eg. $q(x, B) = \int_B q(x, y) \nu(dy) \quad \nu \in \text{Prob}(S_2, \mathcal{B}_2)$

For $f: (S_1 \times S_2, \mathcal{B}_1 \otimes \mathcal{B}_2) \rightarrow (\mathbb{C}, \mathcal{B}(\mathbb{C}))$ bounded or non-negative,

$$x \mapsto \int_{S_2} f(x, y) q(x, dy) \text{ is } \mathcal{B}_1\text{-measurable.}$$

Given random variables $X: (\Omega, \mathcal{F}) \rightarrow (S_1, \mathcal{B}_1)$, $Y: (\Omega, \mathcal{F}) \rightarrow (S_2, \mathcal{B}_2)$

a **regular conditional distribution** of $Y|X$ is a probability kernel $q = q_{Y|X}$

s.t.

$$P(Y \in B | X) = q(X, B) \quad \forall B \in \mathcal{B}_2$$

$$\begin{aligned} E[f(X, Y) | X] \\ = E[f(x, Y)]_{x=X} \end{aligned}$$

Always exists if (S_j, \mathcal{B}_j) are regular Borel spaces.

\Rightarrow If $f \in \mathcal{B}(S_1 \times S_2, \mathcal{B}_1 \otimes \mathcal{B}_2)$,

$$E[f(X, Y) | X] = \int_{S_2} f(x, y) q(x, dy) \Big|_{x=X}$$

Special cases:

- If X, Y are independent, $q_{Y|X}(x, \cdot) = \mu_Y$

$$\text{Ex. } P(Y \in B | X) = \mu_Y(B) = P(Y \in B)$$

- If $(S_1, \mathcal{B}_1, \nu_1)$, $(S_2, \mathcal{B}_2, \nu_2)$ are σ -finite measure spaces, and (X, Y) have a joint density $e_{X, Y}$ wrt $\nu_1 \otimes \nu_2$, then

$$q_{Y|X}(x, B) = \int_B e_{Y|X}(y|x) \nu_2(dy)$$

- If S_1, S_2 are discrete, $q(x, B) = \sum_{y \in B} P(Y=y | X=x)$.

$$q_{Y|X}(y|x)$$

$$= \frac{e_{X, Y}(x, y)}{e_{X, Y}(x, \cdot)}$$

$$\rightarrow e_{X, Y}(x, \cdot)$$

$$\int_{S_2} e_{X, Y}(x, y) \nu_2(dy)$$

Given a probability kernel $q: S_1 \times \mathcal{B}_2 \rightarrow [0, 1]$, there is an associated operator

formerly Lf $\rightarrow (Qf)(x) = \int_{S_2} f(y) q(x, dy)$ "Markov transition operator"

$$\|Qf\|_\infty \leq \|f\|_\infty = \sup |f|.$$

If $S_1 = S_2$, such transition operators are characterized by:

0. $Q: \mathcal{B}(S, \mathcal{B}) \rightarrow \mathcal{B}(S, \mathcal{B})$ is linear.

1. $Q(1) = 1$.

2. $Q(f) \geq 0$ if $f \geq 0$.

3. $f_n \rightarrow f$ boundedly $\Rightarrow Qf_n \rightarrow Qf$ boundedly.

In this case, $q(x, B) = Q(1_B)(x) = \int f(y) q(x, dy) = (Qf)(x)$.

Composing transition operators:

$$(Q_1 Q_2 f)(x) = \int f(z) \int q_1(x, dy) q_2(y, dz)$$

If q is a probability kernel on $(S_1, \mathcal{B}_1), (S_2, \mathcal{B}_2)$ and $\nu \in \text{Prob}(S_1, \mathcal{B}_1)$,
 then $\nu \otimes q \in \text{Prob}(S_1 \times S_2, \mathcal{B}_1 \otimes \mathcal{B}_2)$ is defined by

$$(\nu \otimes q)(B) = \int_{S_1} \nu(dx) \int_{S_2} \mathbb{1}_B(x, y) q(x, dy) \quad \int f d(\nu \otimes q) = \int_{S_1} \nu(dx) \int_{S_2} f(x, y) q(x, dy)$$

If $\mathcal{B}_1, \mathcal{B}_2$ are countably generated, and \tilde{q} is another probability kernel,
 then $\nu \otimes q = \nu \otimes \tilde{q} \iff q(x, \cdot) = \tilde{q}(x, \cdot)$ for ν -a.e. $x \in S_1$.

More generally, if $q_1, \dots, q_n: (S, \mathcal{B})^2 \rightarrow [0, 1]$, $\nu \in \text{Prob}(S, \mathcal{B})$,

$$\int_{S^{n+1}} f d\mu := \int_S \nu(dx_0) \int_S q_1(x_0, dx_1) \int_S q_2(x_1, dx_2) \dots \int_S q_n(x_{n-1}, dx_n) f(x_0, \dots, x_n)$$

defines a probability measure $\mu \in \text{Prob}(S^{n+1}, \mathcal{B}^{\otimes n+1})$.

If $f = f_0 \otimes f_1 \otimes \dots \otimes f_n$,

$$\int_{S^{n+1}} f d\mu = \mathbb{E}_\nu [f_0 Q_1(f_1 Q_2(\dots (f_{n-1} (Q_n f_n) \dots)))]$$