

The Markov Property

Let $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \in T}, \mathbb{P})$ be a filtered probability space,
(with $T = \mathbb{N}$ or $T = \mathbb{R}$).

An adapted stochastic process $X_t: (\Omega, \mathcal{F}_t) \rightarrow (S, \mathcal{B})$
satisfies the **Markov property** if, for $f \in \mathcal{B}(S, \mathcal{B})$,

$$\mathbb{E}[f(X_t) | \mathcal{F}_s] = \mathbb{E}[f(X_t) | X_s] \text{ a.s. for all } s < t \text{ in } T.$$

This is equivalent to

$$\mathbb{E}[f(X_t) | \mathcal{F}_s] = F(X_s) \text{ a.s. for some } F \in \mathcal{B}(S, \mathcal{B})$$

(\Rightarrow)

(\Leftarrow) If $\mathbb{E}_{\mathcal{F}_s}[f(X_t)] = F(X_s)$

Let $\mathcal{F}_t^X := \sigma(X_s : s \leq t)$.

Earlier, we derived a Markov property

$$\mathbb{E}[f(X_t) | \mathcal{F}_s^X] = \mathbb{E}[f(X_t) | X_s] \quad \forall f \in \mathcal{B}(\mathcal{S}, \mathcal{B}), s < t.$$

This is implied by the $(\mathcal{F}_t)_{t \in T}$ -defined Markov property.

Pf.

Note: if T is countable, it suffices to state the Markov property

$$\text{in the form } \mathbb{E}[f(X_{n+1}) | \mathcal{F}_n] = \mathbb{E}[f(X_{n+1}) | X_n]$$

Induction: Suppose $\mathbb{E}[f(X_n) | \mathcal{F}_k] = \mathbb{E}[f(X_n) | X_k]$ for some $n \geq k$.

The Markov property is about the present vs. the past.
But it also tells us about the future.

Def. Given a stochastic process $(X_t)_{t \in T}$, the future σ -field $\mathcal{F}_{\geq s}^X$ is defined as

$$\mathcal{F}_{\geq s}^X := \sigma(X_t : t \geq s)$$

(It is a reverse filtration: if $s_1 \leq s_2$, $\mathcal{F}_{s_1}^X \supseteq \mathcal{F}_{s_2}^X$.)

Prop. Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in T}, \mathbb{P})$ be a filtered probability space, and let $(X_t)_{t \in T}$ be an adapted stochastic process satisfying the Markov property. Then for $s \in T$,

$$\mathbb{E}[Y | \mathcal{F}_s] = \mathbb{E}[Y | X_s] \quad \forall Y \in \mathcal{B}(\Omega, \mathcal{F}_{\geq s}^X).$$

Lemma: Let $M = \{ g_0(X_{t_0}) g_1(X_{t_1}) \dots g_n(X_{t_n}) : n \in \mathbb{N}, s = t_0 < t_1 < \dots < t_n, g_j \in \mathcal{B}(S, \mathcal{B}) \}$.

Then M is a multiplicative system, and $\sigma(M) = \mathcal{F}_{\geq s}^X$.

Pf. Multiplicative system

If $A \in \mathcal{F}_{\geq s}^X$

If $A \in \sigma(M)$

Lemma: Let $H = \{ Y \in \mathcal{B}(\Omega, \mathcal{F}_{\geq s}^X) : \mathbb{E}[Y | \mathcal{F}_s] = \mathbb{E}[Y | X_s] \}$.

Then H is a subspace, contains 1 , and is closed under bounded convergence.

Pf. Subspace:

Contains 1 :

Closed under bounded convergence:

Prop: Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in T}, \mathbb{P})$ be a filtered probability space, and let $(X_t)_{t \in T}$ be an adapted stochastic process satisfying the Markov property. Then for $s \in T$,

$$\mathbb{E}[Y | \mathcal{F}_s] = \mathbb{E}[Y | X_s] \quad \forall Y \in \mathcal{B}(\Omega, \mathcal{F}_{\geq s}^X).$$

Pf. WTS $\mathcal{H} = \mathcal{B}(\Omega, \mathcal{F}_{\geq s}^X)$. By the lemmas, suffices to show $\mathcal{M} \subseteq \mathcal{H}$, where $\mathcal{M} = \{g_0(X_{t_0})g_1(X_{t_1}) \dots g_n(X_{t_n}) : n \in \mathbb{N}, s = t_0 < t_1 < \dots < t_n, g_j \in \mathcal{B}(S, \mathcal{B})\}$.

$$\begin{aligned} \mathbb{E}_{\mathcal{F}_s}[Y] &= \mathbb{E}_{\mathcal{F}_s}[\mathbb{E}_{\mathcal{F}_{t_{n-1}}}[Y]] \\ &= \mathbb{E}_{\mathcal{F}_s}[g_0(X_{t_0}) \dots g_{n-1}(X_{t_{n-1}})] \end{aligned}$$

$$= \mathbb{E}_{\mathcal{F}_s}[F(X_{t_0})]$$

Conditional Independence

Let (Ω, \mathcal{F}, P) be a probability space; $\mathcal{A}, \mathcal{B}, \mathcal{G} \subseteq \mathcal{F}$ sub- σ -fields.

Say that \mathcal{A}, \mathcal{B} are **conditionally independent** given \mathcal{G} if

$$P(A \cap B | \mathcal{G}) = P(A | \mathcal{G}) P(B | \mathcal{G}) \text{ a.s. } \forall A \in \mathcal{A}, B \in \mathcal{B}$$

Equivalently: $E[XY | \mathcal{G}] = E[X | \mathcal{G}] E[Y | \mathcal{G}]$ a.s. $\forall X \in \mathcal{B}(\Omega, \mathcal{A}), Y \in \mathcal{B}(\Omega, \mathcal{B})$

→ Eg. Follows that, if $C \in \mathcal{G}, P(C) > 0$,

$$P(A \cap B | C) = P(A | C) P(B | C) \quad \forall A \in \mathcal{A}, B \in \mathcal{B}. \quad [\text{Why?}]$$

Eg. Let X, Y be iid with law $\frac{1}{2}\delta_1 + \frac{1}{2}\delta_2$. Then $P(X=Y) = \frac{1}{2}$.

$$E[X | X=Y] = E[Y | X=Y] = \frac{E[X \mathbb{1}_{X=Y}]}{P(X=Y)} = \frac{1 \cdot \frac{1}{4} + 2 \cdot \frac{1}{4}}{\frac{1}{2}} = \frac{3}{2}$$

$$E[XY | X=Y] = \frac{E[XY \mathbb{1}_{X=Y}]}{P(X=Y)} = \frac{1 \cdot 1 \cdot \frac{1}{4} + 2 \cdot 2 \cdot \frac{1}{4}}{\frac{1}{2}} = \frac{5}{4}$$

This gives us a "poetic" way to rephrase the Markov property.

Theorem: The Markov property says:

"Conditioned on the present, the past and the future are independent."

More precisely: let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in T}, \mathbb{P})$ be a filtered probability space, and

let $X_t: (\Omega, \mathcal{F}_t) \rightarrow (S, \mathcal{B})$ be an adapted stochastic process. Then

$(X_t)_{t \in T}$ satisfies the Markov property iff, for each $s \in T$,

\mathcal{F}_s and $\mathcal{F}_{\geq s}^X$ are conditionally independent given $\sigma(X_s)$.

Pf. (\Rightarrow) Let $Z \in \mathcal{B}(\Omega, \mathcal{F}_s)$, $Y \in \mathcal{B}(\Omega, \mathcal{F}_{\geq s}^X)$.
 $\mathbb{E}[ZY | \mathcal{F}_s]$

$\therefore \mathbb{E}_{\sigma(X_s)}[\mathbb{E}[ZY | \mathcal{F}_s]]$

(\Leftarrow) [HW].