

Given a Hilbert space  $H$  (like  $L^2(\Omega, \mathcal{F}, P)$ ),  
 and a closed subspace  $K \subseteq H$ , we have the  
 orthogonal projection:

$$P_K : H \rightarrow K$$

a linear transformation, with  $\|P_K(x)\| \leq \|x\|$ ,  
 characterized by

- $P_K(x)$  is the unique  $z \in K$  minimizing  $\|x-z\|$
- $P_K(x)$  is the unique  $z \in K$  s.t.  $x-z \perp K$

$$\leftarrow \text{I.e. } \langle P_K(x), y \rangle = \langle x, y \rangle \quad \forall y \in K$$

$$\mathbb{E}[P_K(x)y] = \mathbb{E}[xy] \quad \text{if } H = L^2(\Omega, \mathcal{F}, P)$$

Recall: if  $\mathcal{G} = \sigma(\{A_n\}_{n=1}^\infty)$  for a partition  $\{A_n\}_{n=1}^\infty$  of  $\Omega$ , then

$$\mathbb{E}[\mathbb{E}_g[x|y]] = \mathbb{E}[xy] \quad \forall y \in L^2(\Omega, \mathcal{G}, P)$$

Prop: Let  $(\Omega, \mathcal{F}, P)$  be a probability space, and let  $\mathcal{G} \subseteq \mathcal{F}$  be a sub- $\sigma$ -field. Then  $L^2(\Omega, \mathcal{G}, P) \subseteq L^2(\Omega, \mathcal{F}, P)$  is a closed subspace.

Pf. We're identifying  $L^2(\Omega, \mathcal{G}, P) = \{X \in L^2(\Omega, \mathcal{F}, P) : X \text{ is } \mathcal{G}\text{-measurable}\}$

Subspace:  $X, Y \in L^2(\Omega, \mathcal{F}, P)$   $\alpha, \beta \in \mathbb{R}$   $\alpha X + \beta Y$  is  $\mathcal{G}$ -measurable.

$$\mathcal{G}\text{-meas. } \|\alpha X + \beta Y\|_{L^2} \leq |\alpha| \|X\|_{L^2} + |\beta| \|Y\|_{L^2} < \infty$$

Closed: If  $X_n$  is  $\mathcal{G}$ -meas,  $X_n \rightarrow X$  in  $L^2(\Omega, \mathcal{F}, P)$

$\exists$  subseq.  $X_{n_k} \rightarrow X$  a.s.

$\Rightarrow X$  is  $\mathcal{G}$ -meas.  
 $\therefore X \in L^2(\Omega, \mathcal{G}, P)$ .

///

Def: If  $X \in L^2(\Omega, \mathcal{F}, P)$  and  $\mathcal{G} \subseteq \mathcal{F}$  is any sub- $\sigma$ -field, the conditional expectation  $E_{\mathcal{G}}[X]$  is the random variable  $= P_{L^2(\Omega, \mathcal{G}, P)}(X)$ .

E.g.  $\Omega = \{1, 2, 3\}$ ,  $\mathcal{F} = 2^{\Omega}$

$$\begin{aligned}\mathcal{G} &= \sigma(\{1, 2\}, \{3\}) \\ &= \{\emptyset, \{1, 2\}, \{3\}, \Omega\}\end{aligned}$$

If  $X$  is  $\mathcal{G}$ -measurable, then  $X^{-1}\{t\} \in \mathcal{G}$   
for each  $t \in \mathbb{R}$ . In particular, with  $t = X(1)$

$$\begin{aligned}t \in X^{-1}(X(1)) &= \{1, 2\} \text{ or } \{1, 2, 3\} \\ X(1) = X(2) &\quad X(1) = X(2) = X(3) \rightarrow \left. \begin{array}{l} \{1, 2\} \\ \{1, 2, 3\} \end{array} \right\} \therefore X(1) = X(2)\end{aligned}$$

$$\begin{matrix} u_1 & u_2 \\ \downarrow & \downarrow \\ \mathbb{1}_{\{1, 2\}} & \mathbb{1}_{\{3\}} \\ \downarrow & \downarrow \end{matrix}$$

$$\text{In fact, for any } P, L^2(\Omega, \mathcal{G}, P) = \mathbb{R}^{\{1, 2, 3\}} \stackrel{\cong}{\rightarrow} \mathbb{R}^3 \supseteq \text{Span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right\}$$

$$L^2(\Omega, \mathcal{G}, P) = \{X \in \mathbb{R}^{\{1, 2, 3\}} : X(1) = X(2)\} \cong \begin{bmatrix} x \\ x \\ y \end{bmatrix}$$

Take  $P = \text{Unif}\{1, 2, 3\}$ . Then  $E[X] = \frac{1}{3}(X(1)\mathbb{1}_{\{1\}} + X(2)\mathbb{1}_{\{2\}} + X(3)\mathbb{1}_{\{3\}})$

$$\begin{aligned}E_{\mathcal{G}}[X] &= \underbrace{\frac{X \cdot u_1}{\|u_1\|^2} u_1 + \frac{X \cdot u_2}{\|u_2\|^2} u_2}_{\frac{2}{3} = P\{\{1, 2\}\}} = \frac{E[X \mathbb{1}_{\{1, 2\}}]}{P\{\{1, 2\}\}} \mathbb{1}_{\{1, 2\}} + \frac{E[X \mathbb{1}_{\{3\}}]}{P\{\{3\}\}} \mathbb{1}_{\{3\}} \\ &\quad \frac{1}{3} = P\{\{3\}\}\end{aligned}$$

What is  $\mathbb{E}_g[X]$ ? It is the  $\mathcal{G}$ -measurable r.v.  
that is closest to  $X$

$$\|X - \mathbb{E}_g[X]\|_{L^2} = \min_{Y \in L^2(\Omega, \mathcal{G}, P)} \|X - Y\|$$

I.e. it is the best guess for  $X$ , using only the information in  $\mathcal{G}$ .

Question: does it only make sense for  $L^2$ ?

Lemma: If  $X \in L^2(\Omega, \mathcal{F}, P)$ , then  $\mathbb{E}[|\mathbb{E}_g[X]|] \leq \mathbb{E}[|X|]$ .

Pf: Set  $Y = \mathbb{E}_g[X]$ . Take  $Z = \text{sgn } Y = \begin{cases} 1, & Y > 0 \\ 0, & Y = 0 \\ -1, & Y < 0 \end{cases} = \frac{Y}{|Y|} \in \mathcal{G}\text{-meas.}$   
b/c  $Y$  is  $\mathcal{G}$ -meas.

"  $K$  bounded  $\therefore L^2$   
 $\therefore Z \in L^2(\Omega, \mathcal{G}, P)$ , and so

$$\mathbb{E}[|Y|] = \mathbb{E}[Y \cdot \text{sgn } Y] = \mathbb{E}[X \cdot \text{sgn } Y] \leq \mathbb{E}[|X \cdot \text{sgn } Y|] \leq \mathbb{E}[|X|].$$

$\overset{\uparrow}{P_K(X)} \quad \overset{\nwarrow}{K}$

///

The lemma shows that  $\|\mathbb{E}_g[X]\|_{L^1} \leq \|X\|_{L^1} \quad \forall X \in L^2$ .

Q.E.D. if we equip  $L^2(\Omega, \mathcal{F}, P)$  with the  $L^1$ -norm,

$\mathbb{E}_g$  is still Lipschitz.

Note that  $L^2 \subseteq L^1$  is dense: given  $X \in L^1$ ,  
 $X \mathbf{1}_{|X| \leq n}$  is bounded and  $\mathbb{P}$ . in  $L^2$ , and  $\|X - X \mathbf{1}_{|X| \geq n}\|_{L^1} = \mathbb{E}[|X| \mathbf{1}_{|X| \geq n}] \xrightarrow{n \rightarrow \infty} 0$  DCT

Def: If  $X \in L^1(\Omega, \mathcal{F}, P)$  and  $\mathcal{G} \subseteq \mathcal{F}$ , define  $\mathbb{E}_{\mathcal{G}}[X]$  as follows:

↪ Take any sequence  $X_n \in L^2(\Omega, \mathcal{G}, P)$  s.t.  $\|X_n - X\|_{L^1} \rightarrow 0$

↪ Define  $\mathbb{E}_{\mathcal{G}}[X] := L^1\text{-}\lim_{n \rightarrow \infty} \mathbb{E}_{\mathcal{G}}[X_n] = L^1\text{-}\lim_{n \rightarrow \infty} P_{L^2(\Omega, \mathcal{G}, P)}(X_n)$

• Exists:  $\|\mathbb{E}_{\mathcal{G}}[X_n] - \mathbb{E}_{\mathcal{G}}[X_m]\|_{L^1} = \|\mathbb{E}_{\mathcal{G}}[X_n - X_m]\|_{L^1} \leq \|X_n - X_m\|_{L^1} \rightarrow 0$  as  $n, m \rightarrow \infty$ .

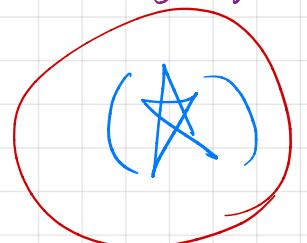
∴  $\{\mathbb{E}_{\mathcal{G}}[X_n]\}_{n=1}^{\infty}$  is  $L^1$ -Cauchy, ∴ exists.

• Well-defined: if  $X_n, Y_n \rightarrow X$  in  $L^1$ , then

$$\|\mathbb{E}_{\mathcal{G}}[X_n] - \mathbb{E}_{\mathcal{G}}[Y_n]\|_{L^1} = \|\mathbb{E}_{\mathcal{G}}[X_n - Y_n]\|_{L^1} \leq \|X_n - Y_n\|_{L^1} \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Prop: (Averaging property / characterization)

For  $X \in L^1(\Omega, \mathcal{F}, P)$  and  $\mathcal{G} \subseteq \mathcal{F}$ ,  $E_{\mathcal{G}}[X]$  is the unique  $L^1(\Omega, \mathcal{G}, P)$  random variable with the property:



$$E[E_{\mathcal{G}}[X]Y] = E[XY] \quad \forall Y \in \mathcal{B}(\Omega, \mathcal{G}).$$

Pf. If  $X \in L^2$ ,  $(*)$  holds by def<sup>n</sup> of orth-proj. (b/c  $\mathcal{B}(\Omega, \mathcal{G}) \subseteq L^2(\Omega, \mathcal{G}, P)$ ).

In general,  $E_{\mathcal{G}}[X] = L^1 - \lim_{n \rightarrow \infty} E_{\mathcal{G}}[X_n]$  for any  $X_n \rightarrow X$  in  $L^1$

$$\begin{aligned} & \because E_{\mathcal{G}}[X_n]Y \rightarrow E_{\mathcal{G}}[X]Y \\ & \qquad \qquad \qquad \text{in } L^1 \\ & \qquad \qquad \qquad X_nY \rightarrow XY \end{aligned}$$



$$\therefore E[E_{\mathcal{G}}[X]Y - XY] = \lim_{n \rightarrow \infty} E[E_{\mathcal{G}}[X_n]Y - X_nY] = 0.$$

Conversely, if  $Z_1, Z_2 \in L^1(\Omega, \mathcal{G}, P)$  each satisfy

$$E[Z_1Y] = E[Z_2Y] = E[XY] \quad \forall Y \in \mathcal{B}(\Omega, \mathcal{G})$$

then  $E[(Z_1 - Z_2)Y] = 0$ . Take  $Y = \text{sgn}(Z_1 - Z_2) \mathbb{1}_{|Z_1 - Z_2| \leq n} \in \mathcal{B}(\Omega, \mathcal{G})$

$$\begin{aligned} & \because 0 = E[|Z_1 - Z_2| \mathbb{1}_{|Z_1 - Z_2| \leq n}] \xrightarrow[\text{DCT}]{n \rightarrow \infty} E[|Z_1 - Z_2|] \Rightarrow Z_1 = Z_2 \in L^1. \quad // \end{aligned}$$

Theorem: (Main Properties of Conditional Expectation)

Let  $(\Omega, \mathcal{F}, P)$  be a probability space, and  $\mathcal{G} \subseteq \mathcal{F}$  a sub- $\sigma$ -field. The linear transformation

$$E_{\mathcal{G}} : L^1(\Omega, \mathcal{F}, P) \rightarrow L^1(\Omega, \mathcal{G}, P)$$

satisfies:

- ✓ 1. (Monotonicity) if  $X \leq Y$  a.s. [P] then  $E_{\mathcal{G}}[X] \leq E_{\mathcal{G}}[Y]$  a.s. [P].  $E_{\mathcal{G}}[M] = M$
- ✓ 2. (Ave-m eq.)  $|E_{\mathcal{G}}[X]| \leq E_{\mathcal{G}}[|X|]$  a.s. [P]. If  $|X| \leq M$  a.s.  $|E_{\mathcal{G}}[X]| \leq M$  a.s.
- ✓ 3. (Averaging)  $E[E_{\mathcal{G}}[X|Y]] = E[XY] \quad \forall Y \in \mathcal{B}(\Omega, \mathcal{G})$
- 4. (Product Rule) If  $Y \in \mathcal{B}(\Omega, \mathcal{G})$ ,  $E_{\mathcal{G}}[XY] = E_{\mathcal{G}}[X] \cdot Y$ .
- 5. (Tower Property) If  $\mathcal{H} \subseteq \mathcal{G} \subseteq \mathcal{F}$  are all  $\sigma$ -fields, then

$$E_{\mathcal{G}}[E_{\mathcal{H}}[X]] = E_{\mathcal{H}}[E_{\mathcal{G}}[X]] = E_{\mathcal{H}}[X].$$

$$z = E_{\mathcal{G}}[Y-X]$$

Pf. 1.  $E[E_{\mathcal{G}}[X|B]] = E[X|B] \leq E[Y|B] = E[E_{\mathcal{G}}[Y|B]] \quad \forall B \in \mathcal{G}. \quad \downarrow$

So, suffices to show that, if  $Z \in L^1(\Omega, \mathcal{G}, P)$  and  $E[Z|B] \geq 0 \quad \forall B \in \mathcal{G}$  then  $Z \geq 0$  a.s. [P]

$$\begin{aligned} B = \{Z < 0\} \in \mathcal{G} \quad \therefore 0 \leq E[Z|_{\{Z < 0\}}] \leq 0 \Rightarrow E[Z|_{\{Z < 0\}}] = 0. \quad \text{A } P(Z < 0) = 0. \\ 0 = E[-Z|_{\{Z < 0\}}] = E[IZ|_{\{Z < 0\}}] \Rightarrow |Z|1_{\{Z < 0\}} \geq 0 \text{ a.s.} \end{aligned}$$

2.  $X \leq |X|$  and  $-X \leq |X| \therefore$  by (1)  $\downarrow$

$\therefore E_g[X] \leq E_g[|X|]$  and

$E_g[-X] \leq E_g[|X|]$  a.s.

$\Rightarrow |E_g[X]| \leq E_g^{|X|}[|X|]$ . a.s.

3.  $\checkmark$

4. Let  $Y, Z \in B(\Omega, \mathcal{F})$ . Then

$$E[E_g[X](Y \cdot Z)] = E[\underbrace{E_g[X] \cdot YZ}_{\text{---}}] \stackrel{(3)}{=} E[\underbrace{XYZ}_{\text{---}}] \stackrel{(3)}{=} E[E_g[XY]Z]$$

$$\therefore E[(Y \underbrace{E_g[X]}_U - E_g[XY])Z] = 0 \quad \forall Z \in B(\Omega, \mathcal{F})$$

Take  $Z = \text{sgn } U$   $\|U\|_{L^1}$  s.t.  
 $Q = E[|U| \|U\|_{L^1}] \xrightarrow{\text{DCT}} E[|U|]$   
 $\Rightarrow U < 0$  a.s.

5.  $E_g[E_H[X]] = E_H[E_g[X]] = E_H[X]$  holds for  $X \in L^2$  by orth. proj. thm.

Now approximate  $X \in L^2$  by  $X_n \in L^2$ ,  
and be careful.