

Given (Ω, \mathcal{F}, P) and $A \in \mathcal{F}$ with $P(A) > 0$,
 we have the conditioned probability measure

$$P_A(B) = P[B|A] = \frac{P(A \cap B)}{P(A)}$$

We can then take integrals of random variables $X \in L^1(\Omega, \mathcal{F}, P_A)$

$$E_A[X] = E[X|A] = \int X dP_A$$

Lemma: $L^1(P) = L^1(P_A)$, and $E_A[X] = \frac{E[X \cdot \mathbb{1}_A]}{P(A)}$

Pf. If X is simple, $X = \sum_j \alpha_j \mathbb{1}_{B_j}$, then

$$\int X dP_A = \sum_j \alpha_j (P_A(B_j)) = \sum_j \alpha_j \frac{P(A \cap B_j)}{P(A)} = \frac{1}{P(A)} \int \sum_j \alpha_j \mathbb{1}_{B_j \cap A} dP$$

For general $X = X^+ - X^-$ $X_n^+ + X_n^- \leq X^+ + X^- = |X| \in L^1$

$E[X^+|A]/P(A)$ $0 < X_n^\pm \leq X^\pm$ $|X_n^+ - X_n^-|$ $(\sum_j \alpha_j \mathbb{1}_{B_j}) \mathbb{1}_A$

$\int X_n^+ \mathbb{1}_A dP - \int X_n^- \mathbb{1}_A dP$ $\int (X_n^+ - X_n^-) dP_A \rightarrow \int X dP_A$ \parallel $= \frac{E[X \mathbb{1}_A]}{P(A)}$

If $\{A_n\}_{n=1}^{\infty}$ is a partition of Ω by events with $P(A_n) > 0$, we can string the different E_{A_n} functionals together into a single function:

$$E_{\{A_n\}_{n=1}^{\infty}}[X] = \sum_{n=1}^{\infty} E_{A_n}[X] \mathbb{1}_{A_n}$$

Eq. $\omega \mapsto \begin{cases} \vdots \\ E_{A_n}[X] = \frac{E[X \mathbb{1}_{A_n}]}{P(A_n)} \text{ for } \omega \in A_n. \\ \vdots \end{cases}$

Labeling: instead of indexing this by the partition $\{A_n\}_{n=1}^{\infty}$, it is more convenient (and suggestive) to label it by $\mathcal{G} = \sigma(\{A_n\}_{n=1}^{\infty})$. This makes sense because:

Exercise: If $A_n \in \mathcal{F}$ with $\Omega = \bigsqcup_{n=1}^{\infty} A_n$, then

$$\sigma(\{A_n\}_{n=1}^{\infty}) = \left\{ \bigsqcup_{n \in \Lambda} A_n : \Lambda \subseteq \mathbb{N} \right\}$$

Thus, we can "recover" the partition from \mathcal{G} (minimal generating set)

Cor: If $\mathcal{G} = \sigma(\{A_n\}_{n=1}^{\infty})$ for some partition $\{A_n\}_{n=1}^{\infty}$,
then $\mathbb{E}_{\mathcal{G}}[X]$ is \mathcal{G} -measurable.

Pf: $\mathbb{E}_{\mathcal{G}}[X] = \sum_{n=1}^{\infty} \mathbb{E}_{A_n}[X] \mathbb{1}_{A_n}$ is a linear combination
of the indicator functions $\mathbb{1}_{A_n} \in \mathcal{G}$. ///

$$\sigma(\mathbb{E}_{\mathcal{G}}[X]) = \mathcal{G}.$$

Note: even in this special case where \mathcal{G} is generated
by a countable partition, it is not practically possible
to recover the partition from \mathcal{G} (unless \mathcal{G} , and
 \therefore the partition, is finite)

(Motivating) Eg. Suppose $Y: \Omega \rightarrow S$ is a random variable whose state space S is countable, and $P(Y=s) > 0$ for each $s \in S$. Then $\{Y^{-1}(s) = s \in S\}$ forms a partition of Ω .

$$\sigma\left\{\overset{\parallel}{Y^{-1}(s)} = s \in S\right\} \\ \overset{\parallel}{\sigma(Y)}$$

For $X \in L^1(\Omega, \mathcal{F}, P)$,

$$E[X|Y] = E[X | \sigma(Y)] = \sum_{s \in S} E_{\{Y=s\}}[X] \mathbb{1}_{\{Y=s\}} = \sum_{s \in S} \frac{E[X \cdot \mathbb{1}_{Y=s}]}{P(Y=s)} \mathbb{1}_{\{Y=s\}}$$

$$E[X|Y](\omega) = \frac{E[X \cdot \mathbb{1}_{Y=Y(\omega)}]}{P(Y=Y(\omega))}$$

$E[X|Y]$ is $\sigma(Y)$ -measurable \leftarrow only depends on ω through $Y(\omega)$

\therefore by Doob-Dynkin, $E[X|Y] = g(Y)$ for some $g: S \rightarrow \mathbb{R}$

$$g(s) = "E[X|Y=s]" \\ = E_{P_{\{Y=s\}}}[X]$$

There is a more "invariant" way to define conditional expectation, owing to the following.

Prop: Let $\{A_n\}_{n=1}^{\infty}$ be a partition of Ω by positive probability events, and set $\mathcal{G} = \sigma(\{A_n\}_{n=1}^{\infty})$.
 If $X \in L^2(\Omega, \mathcal{F}, P)$ and $Y \in L^2(\Omega, \mathcal{G}, P)$, then

$$\mathbb{E}[XY] = \mathbb{E}[\mathbb{E}_{\mathcal{G}}[X]Y].$$

Pf. Step 1: the case that Y is simple. So $Y = \sum_j \beta_j \mathbb{1}_{B_j} \leftarrow B_j \in \mathcal{G}$

$$\therefore \mathbb{E}[XY] = \sum_{k=1}^{\infty} \beta'_k \mathbb{E}[X \mathbb{1}_{A_k}]$$

$$\mathbb{E}_{\mathcal{G}}[X] = \sum_{j=1}^{\infty} \mathbb{E}_{A_j}[X] \mathbb{1}_{A_j}$$

$$Y = \sum_{k=1}^{\infty} \beta'_k \mathbb{1}_{A_k}$$

$$B_j = \bigsqcup_{k \in \Lambda_j} A_k$$

$$\text{So } \mathbb{E}[\mathbb{E}_{\mathcal{G}}[X]Y] = \sum_{j,k=1}^{\infty} \mathbb{E}_{A_j}[X] \beta'_k \mathbb{E}[\mathbb{1}_{A_j} \mathbb{1}_{A_k}]$$

$$= \sum_{k=1}^{\infty} \mathbb{E}_{A_k}[X] \beta'_k \mathbb{P}(A_k) = \beta'_k \mathbb{E}[X \mathbb{1}_{A_k}]$$

$$\delta_{jk} \mathbb{E}[\mathbb{1}_{A_k}] = \delta_{jk} \mathbb{P}(A_k)$$

Step 2: If $Y \in L^2(\Omega, \mathcal{G}, P) \subseteq L^1(\Omega, \mathcal{G}, P)$,

\exists sequence of simple Y_n (\mathcal{G} -measurable) s.t.

$$Y_n \rightarrow Y \text{ a.s. and } |Y_n| \leq |Y| \in L^2$$

$\therefore XY_n \rightarrow XY$ a.s. and $|XY_n| \leq |XY| \in L^1$ b/c $XY \in L^1$ by C-S

\therefore By DCT, $E[XY_n] \rightarrow E[XY]$

$$|E_{\mathcal{G}}[XY_n]| \leq |E_{\mathcal{G}}[XY]| \in L^1$$

DCT $E[E_{\mathcal{G}}[XY_n]] \rightarrow E[E_{\mathcal{G}}[XY]]$

Note: $\|E_{\mathcal{G}}[X]\|_{L^2}^2 = E\left[\left(\sum_{j=1}^{\infty} E_{A_j}[X] \mathbb{1}_{A_j}\right)^2\right] = \sum_{j=1}^{\infty} E_{A_j}[X]^2 P(A_j) \leq \sum_{j=1}^{\infty} E[X^2 \mathbb{1}_{A_j}] = E[X^2] = \|X\|_{L^2}^2$

$$\begin{aligned} & (E[X \mathbb{1}_{A_j} - \mathbb{1}_{A_j}])^2 \\ & \leq E[(X \mathbb{1}_{A_j})^2] E[\mathbb{1}_{A_j}^2] \\ & = E[X^2 \mathbb{1}_{A_j}] P(A_j) \end{aligned}$$

$$\rightarrow \left(\frac{E[X \mathbb{1}_{A_j}]}{P(A_j)}\right)^2 \leq \frac{E[X^2 \mathbb{1}_{A_j}]}{P(A_j)}$$

$$\begin{aligned} & = E[X^2] \\ & = \|X\|_{L^2}^2 \end{aligned}$$

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