

II. Introduction to Bounded Arithmetic and Witnessing

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Bounded arithmetic and bounded quantifiers

Language of first-order theory of bounded includes:

$$0, S, +, \cdot, \leq, |x| := \lceil \log_2(x + 1) \rceil, \lfloor \frac{1}{2}x \rfloor, x \# y := 2^{|x| \cdot |y|}.$$

Sometimes also add all polynomial time functions and relations.

Axioms can include (among others):

- (a) Defining (equational) axioms for functions and relations, "BASIC".
- (b) Restricted forms of induction.

Definition

A *bounded* quantifier is of the form $(\forall x \leq t)$ or $(\exists x \leq t)$. It is *sharply bounded* provided t has the form $|s|$. A formula is *bounded* or *sharply bounded* provided all its quantifiers are bounded or sharply bounded (resp.).

Definition

$\Delta_0^b = \Sigma_0^b = \Pi_0^b$: Sharply bounded formulas

Σ_{i+1}^b : Closure of Π_i^b under existential bounded quantification and arbitrary sharply bounded quantification, modulo prenex operations.

Π_{i+1}^b is defined dually.

Σ_i^b, Π_i^b define exactly the predicates at the i -th level of the polynomial hierarchy (PH), if $i \geq 1$.

Thus, Σ_1^b and Π_1^b define exactly the NP and coNP sets.

Induction axioms

Let formulas A be in Ψ , we have the following kinds of induction:

$$\Psi\text{-IND:} \quad A(0) \wedge (\forall x)(A(x) \rightarrow A(x + 1)) \rightarrow (\forall x)A(x).$$

$$\Psi\text{-PIND:} \quad A(0) \wedge (\forall x)(A(\lfloor \frac{1}{2}x \rfloor) \rightarrow A(x)) \rightarrow (\forall x)A(x).$$

$$\Psi\text{-LIND:} \quad A(0) \wedge (\forall x)(A(x) \rightarrow A(x + 1)) \rightarrow (\forall x)A(|x|).$$

Definition (Fragments of bounded arithmetic, B'85)

$$S_2^i: \text{BASIC} + \Sigma_i^b\text{-PIND.}$$

$$T_2^i: \text{BASIC} + \Sigma_i^b\text{-IND.}$$

$$S_2 = \cup_i S_2^i \text{ and } T_2 = \cup_i T_2^i.$$

Note T_2 is essentially $I\Delta_0 + \Omega_1$. [Parikh'71, Wilkie-Paris'87]

Theorem (B'85, B'90)

- (a) $S_2^1 \subseteq T_2^1 \preceq_{\forall\Sigma_2^b} S_2^2 \subseteq T_2^2 \preceq_{\forall\Sigma_3^b} S_2^3 \subseteq \dots$
 (b) *Thus, $S_2 = T_2$.*
 (c) $S_2^1 + \Sigma_i^b\text{-LIND}$ equals S_2^i .

More axioms:

Φ -MIN: $(\exists x)A(x) \rightarrow (\exists x)(A(x) \wedge (\forall y < x)\neg A(y))$.

Φ -LMIN: $(\exists x)A(x) \rightarrow (\exists x)(A(x) \wedge (\forall y)(|y| < |x| \rightarrow \neg A(y)))$.

Φ -replacement:

$$(\forall x \leq |t|)(\exists y \leq s)A(x, y) \rightarrow (\exists w)(\forall x \leq |t|)A(x, \beta(x, w)).$$

Φ -strong replacement:

$$(\exists w)(\forall x \leq |t|)[(\exists y \leq s)A(x, y) \leftrightarrow A(x, \beta(x, w))].$$

$$\Sigma_i^b\text{-IND} \iff \Pi_i^b\text{-IND} \iff \Sigma_i^b\text{-MIN} \iff \Pi_{i-1}^b\text{-MIN} \iff \Delta_{i+1}^b\text{-IND}$$

$$\Downarrow$$

$$\Sigma_i^b\text{-PIND} \iff \Pi_i^b\text{-PIND} \iff \Sigma_i^b\text{-LIND} \iff \Pi_i^b\text{-LIND}$$

$$\Updownarrow$$

$$\Sigma_i^b\text{-LMIN} \iff (\Sigma_{i+1}^b \cap \Pi_{i+1}^b)\text{-PIND} \iff_1 \text{strong } \Sigma_i^b\text{-replacement}$$

$$\Downarrow$$

$$\Sigma_{i-1}^b\text{-IND}$$

$$S_2^i \preceq_{\forall \Sigma_i^b} T_2^{i-1}$$

$$S_2^i \preceq_{\forall \mathcal{B}(\Sigma_i^b)} T_2^{i-1} + \Sigma_i^b\text{-replacement}$$

$$\Sigma_1^b\text{-PIND} + \Sigma_{i+1}^b\text{-replacement} \implies \Sigma_i^b\text{-PIND} \implies \Sigma_i^b\text{-replacement}$$

Open: The exact relative strength of Σ_i^b -replacement.

Provably total functions and Σ_1^b -definable functions

Definition

Let R be a bounded theory. A function $f : \mathbb{N} \rightarrow \mathbb{N}$ is *provably total* in R provided there is a formula $A_f(x, y)$ that defines the graph of f such that R proves $(\forall x)(\exists! y)A_f(x, y)$, with A_f polynomial time computable.

Definition

f is Σ_1^b -definable by R , provided there is a Σ_1^b -formula $A(x, y)$ such that

1. $R \vdash (\forall x)(\exists y \leq t)A(x, y)$ for some term t .
2. $R \vdash (\forall x)(A(x, y) \wedge A(x, z) \rightarrow y = z)$.
3. $A(x, y)$ defines the graph of f .

Thm. Any Σ_1^b -definable function in S_2^i or T_2^i can be introduced conservatively into the language of the theory with its defining axiom, and be used freely in induction formulas.

Theorem (B'85)

1. S_2^1 can Σ_1^b -define every polynomial time function.
2. S_2^i can Σ_i^b -define every function which is polynomial time computable with an oracle from Σ_{i-1}^P .

(The converse holds too.)

Hence, we can w.l.o.g. assume that all polynomial time functions are present in the language of bounded arithmetic.

Similar definitions and results hold for predicates.

Definition

A predicate P is Δ_i^b -definable in R provided there are a Σ_i^b -formula A and Π_i^b -formula B which are R -provably equivalent and which define the predicate P .

Theorem (B'85)

*Every polynomial time predicate is Δ_1^b -definable by S_2^1 .
Every predicate which is polynomial time computable with an oracle from Σ_{i-1}^b is Δ_i^b -definable in S_2^i .*

(Again, a converse holds.)

Thus, every polynomial time predicate can be conservatively introduced to S_2^i or T_2^i with its defining axioms, and used freely in induction axioms.

Witnessing Theorem for S_2^i Theorem (Main Theorem for S_2^i , B'85)

Let $i \geq 1$. Suppose f is Σ_i^b -definable by S_2^i . Then f is computable in $P^{\Sigma_{i-1}^P}$, that is, in polynomial time with an oracle for Σ_{i-1}^P .

For $i = 1$, f is in P , polynomial time computable.

This gives an exact characterization of the functions that are Σ_i^b -definable in S_2^i .

For $i = 1$, the Σ_1^b -definable functions of S_2^1 are precisely the polynomial computable functions.

Likewise, the Δ_1^b -definable predicates of S_2^1 are precisely the predicates that are provably in $\text{NP} \cap \text{coNP}$.

Open: Give a more satisfactory account of the functions that are Σ_i^b -definable in S_2^i , $i > 1$. That is, of the provably total functions of these theories. (Note the uniqueness condition.)

We now start the proof of the Main Theorem.

Proof idea: Form a free-cut free proof, in which all formulas are in Σ_i^b . The free-cut free proof is then essentially an algorithm for the function f .

The proof is considerably simplified by working with *strict* Σ_i^b -formulas, denoted $s\Sigma_i^b$ for short. These are of the form:

$$(\exists x_1 \leq t_1)(\forall x_2 \leq t_2) \cdots (Qx_i \leq t_i)B(\vec{x})$$

where B is sharply bounded, and the quantifiers alternate in type (and subformulas of these formulas).

Thm. S_2^i can equivalently be formulated with $s\Sigma_i^b$ -PIND, provided \div and MSP are added to the language.

Proof idea: Careful bootstrapping, plus use of replacement.

To prove the witnessing theorem, by free-cut elimination, it suffices to consider sequent calculus proofs in which every formula is an $s\Sigma_i^b$ -formula (including, via pairing functions, the final, proved formula). Henceforth, fix $i > 0$.

Definition

Let $A(\vec{c})$ be $s\Sigma_i^b$. The predicate $Wit_A(\vec{c}, u)$ is defined so that

- If A is $(\exists x \leq t)B(\vec{c}, x)$, $B \notin \Sigma_{i-1}^b$, then $Wit_A(\vec{c}, u)$ is the formula $u \leq t \wedge B(\vec{c}, u)$.
- If A is in Π_{i-1}^b , then $Wit_A(\vec{c}, u)$ is just $A(\vec{c})$.

The following is trivial since we are working with strict formulas.

Fact: $A(\vec{c}) \leftrightarrow (\exists u)Wit_A(\vec{c}, u)$.

Fact: Wit_A is a Π_{i-1}^b -formula (or Δ_1^b , when $i = 1$.)

A cedent is a set of formulas. If Γ and Δ are cedents, then $\Gamma \rightarrow \Delta$ is a *sequent*. Its meaning is that the conjunction of Γ implies the disjunction of Δ .

Letting $\Gamma = A_1, \dots, A_k$, then $Wit_\Gamma(\vec{c}, u)$ is the statement:

$$\bigwedge_{i=1}^k Wit_{A_i}(\vec{c}, (u)_i).$$

For $\Delta = B_1, \dots, B_\ell$, $Wit_\Delta(\vec{c}, u)$ is the statement

$$\bigvee_{j=1}^{\ell} ((u)_1 = j \wedge Wit_{B_j}(\vec{c}, (u)_2))$$

The notation $(u)_i$ means $\beta(i, u)$, the i -entry in the sequence coded by u . That is, $u = \langle u_1, \dots, u_k \rangle$ in the first case, and $u = \langle u_1, u_2 \rangle$ in the second case.

Theorem (Witnessing Lemma)

If $\Gamma \rightarrow \Delta$ is an S_2^i -provable sequent of $s\Sigma_i^b$ formulas with free variables \vec{c} , then there is a function $f(\vec{c}, u)$ which is Σ_i^b -definable in S_2^i and computable in polynomial time with an oracle for Σ_{i-1}^b such that S_2^i proves

$$\text{Wit}_\Gamma(\vec{c}, u) \rightarrow \text{Wit}_\Delta(\vec{c}, f(\vec{c}, u)).$$

The theorem is proved by induction on the number of lines in a free-cut free S_2^i -proof P of $\Gamma \rightarrow \Delta$. The base cases are the equational axioms defining the symbols of the language. Since witnesses for Δ_0^b -formulas are trivial, these cases are all trivial.

The induction step splits into cases depending on the last inference of the proof P .

Case (1): Last inference is $\exists \leq$:right.

$$\frac{\Gamma \rightarrow \Delta, A(\vec{c}, s)}{s \leq t, \Gamma \rightarrow \Delta, (\exists x \leq t)A(\vec{c}, x)}$$

The formula A is $s\Pi_{i-1}^b$. The induction hypothesis gives a function f , which accepts witnesses for Γ and produces a witness either making a formula in Δ true or making $A(\vec{c}, s)$ true. Modify f , so that in the latter case, it returns $\langle \ell, s \rangle$.

$$g(\vec{c}, u) = \begin{cases} f(\vec{c}, \text{cdr}(u)) & \text{if } (f(\vec{c}, \text{cdr}(u)))_1 < \ell \\ \langle \ell, s(\vec{c}) \rangle & \text{if } (f(\vec{c}, \text{cdr}(u)))_1 = \ell. \end{cases}$$

(The “*cdr*” operation strips the first entry from a sequence.)

Case (2): Last inference is $\exists \leq$:left.

$$\frac{b \leq t, A(\vec{c}, b), \Gamma \rightarrow \Delta}{(\exists x \leq t)A(\vec{c}, x), \Gamma \rightarrow \Delta}$$

where A is $s\Pi_{i-1}^b$ but not $s\Sigma_{i-1}^b$. Let f be given by the induction hypothesis. Define g by

$$g(\vec{c}, u) = f(\vec{c}, (u)_1, \langle 0 \rangle * u)$$

(The “*” operation is sequence concatenation.)

Case (2'): Last inference is $\exists \leq$:left.

$$\frac{b \leq t, A(\vec{c}, b), \Gamma \rightarrow \Delta}{(\exists x \leq t)A(\vec{c}, x), \Gamma \rightarrow \Delta}$$

where A is $s\Pi_{i-2}^b$. Let f be given by the induction hypothesis. Let $\mu_A(\vec{c})$ equal the least $x \leq t(\vec{c})$ such that $A(\vec{c}, x)$ is true, or equal $t + 1$ if no such x exists.

Define g as

$$g(\vec{c}, u) = f(\vec{c}, \mu_A(\vec{c}), \langle 0 \rangle * u).$$

Note that μ_A is computable in polynomial time with an oracle for $s\Sigma_{i-1}^b$.

A similar argument applies for $\forall \leq$: *right* inferences.

Case (3): Last inference is PIND.

$$\frac{A(\lfloor \frac{1}{2}b \rfloor), \Gamma \rightarrow \Delta, A(b)}{A(0), \Gamma \rightarrow \Delta, A(t)}$$

where $A \in \Sigma_i^b \setminus \Sigma_{i-1}^b$. Let f be given by the induction hypothesis. Define

$$h(\vec{c}, b, u) = \begin{cases} h(\vec{c}, \lfloor \frac{1}{2}b \rfloor, u) & \text{if } (h(\vec{c}, \lfloor \frac{1}{2}b \rfloor, u))_1 < \ell \\ f(\vec{c}, b, \langle (h(\vec{c}, \lfloor \frac{1}{2}b \rfloor, u))_2 \rangle * \text{cdr}(u)), & \text{otherwise} \end{cases}$$

and $h(\vec{c}, 0, u) = \langle \ell, (u)_1 \rangle$. h can be defined by *limited iteration on notation* and is polynomial time computable relative to f . Here, ℓ is the number of formulas in the antecedent.

Then set $g(\vec{c}, u) = h(\vec{c}, t(\vec{c}), u)$.

Q.E.D.

TFNP problems of S_2^1

Corollary

If $R(x, y) \in P$ and $S_2^1 \vdash (\forall x)(\exists y)R(x, y)$, then $R(x, y)$ is computable by some polynomial time function, provably in S_2^1 . That is, for some Σ_1^b -defined, hence ptime, function f , $S_2^1 \vdash \forall x R(x, f(x))$.

Proof: Parikh's theorem gives a polynomial bound on y that is provable in S_2^1 . Then, the corollary is immediate from the Witnessing Lemma. □

$$T_2^i \preceq_{\Sigma_{i+1}^b} S_2^{i+1}$$

Next we sketch the proof of the fact that S_2^{i+1} is $\forall\Sigma_{i+1}^b$ -conservative over T_2^i .

Lemma

$$T_2^i \vdash \Pi_i^b\text{-IND.}$$

Proof. Given $A(x)$ in Π_i^b , instead of using induction on $A(x)$ from $x = 0$ up to $x = t$, use induction on $\neg A(t \dot{-} x)$ with t fixed.

Lemma

$$T_2^i \vdash \Sigma_i^b\text{-minimization.}$$

Proof. Suppose $(\exists x)A(x)$, but there is no least such x . Use induction on the Π_i^b -formula $(\forall x < a)\neg A(x)$ to get a contradiction.

Lemma

T_2^i can Σ_{i+1}^b -define every function in $P^{\Sigma_i^b}$.

Proof. (Idea.) Let f be in $P^{\Sigma_i^b}$. Without loss of generality, f is computed using a “witness oracle” that when queried “ $\exists x \leq t. A(x, n)$?” either returns a value for $x \leq t$ that makes A true, or returns $t + 1$ indicating no such x exists.

A consistent computation for f is a computation based on a sequence of oracle answers such that any response $x \leq t$ does satisfy A (but answers “ $t + 1$ ” may be incorrect).

The property of being a consistent computation is Π_{i-1}^b . Order consistent computations lexicographically; T_2^i , via Σ_i^b -minimization, proves there exists a minimum consistent computation. And, that this consistent computation has all oracle answers correct. It is straightforward to check that the minimum consistent computation is Σ_{i+1}^b -definable.

Theorem (B'90)

S_2^{i+1} is $\forall\Sigma_{i+1}^b$ -conservative over T_2^i .

Proof. (Idea) Repeat the proof of the Witnessing Lemma for S_2^{i+1} , but now the conclusion is that T_2^i proves the witnessing sequent (instead of S_2^{i+1}):

$$\text{Wit}_\Gamma(\vec{c}, u) \rightarrow \text{Wit}_\Delta(\vec{c}, f(\vec{c}, u)).$$

It can be checked that T_2^i can formalize all the reasoning that was earlier formalized in S_2^{i+1} .

T_2^1 and PLS [BK'94]

A *Polynomial Local Search* PLS is formalized in S_2^1 provided its feasible set, initial point function, neighborhood function, and cost function are Σ_1^b -defined (as ptime functions).

Theorem

T_2^1 can prove that any (formalized) PLS problem is total.

Proof: By Σ_1^b -minimization, T_2^1 can prove there is a minimum cost value c_0 satisfying

$$(\exists s \leq b(x))(F(x, s) \wedge c(x, s) = c_0).$$

Choosing s that realizes the cost c_0 gives either a solution to the PLS problem or a place where the PLS conditions are violated. \square

Open: Can T_2^1 witness any PLS problem with a Σ_1^b -definable (single-valued) function?

Theorem (BK'94)

If $A \in \Sigma_1^b$ and $T_2^1 \vdash (\forall x)(\exists y)A(x, y)$, then there is a PLS problem R such that T_2^1 proves

$$(\forall x)(\forall y)(R(x, y) \rightarrow A(x, (y)_1)).$$

If $A \in \Delta_1^b$, then can replace “ $(y)_1$ ” with just “ y ”.

This gives an exact complexity characterization of the $\forall\Sigma_1^b$ -definable functions of T_2^1 , in terms of PLS-computability.

Theorem (Witnessing Lemma)

If $\Gamma \rightarrow \Delta$ is a T_2^1 -provable sequent of $s\Sigma_1^b$ formulas with free variables \vec{c} , then there is a PLS problem $R(\langle \vec{c}, u \rangle, v)$ so that T_2^1 proves

$$\text{Wit}_\Gamma(\vec{c}, u) \wedge R(\langle \vec{c}, u \rangle, v) \rightarrow \text{Wit}_\Delta(\vec{c}, v).$$

Proof idea: Use a free-cut free T_2^1 -proof, proceed by induction on number of inferences in the proof. Arguments are similar to what was used to prove the witnessing lemma for S_2^i ($i = 1$ case). Most cases just require closure of PLS under polynomial time operations. However, induction (Σ_1^b -IND inference) now requires exponentially long iteration: this is handled via the exponentially many possible cost values. \square

The Theorem and Witnessing Lemma generalize to $i > 1$ with $\text{PLS}^{\Sigma_{i-1}^b}$. The fourth talk will improve on this, however.

Some selected references

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