## 22. Group Actions

Even though one defines a group abstractly the only sensible way to think about a group is as a group of symmetries, or what comes to the same thing, as a group of permutations.

Group actions are to permutations as equivalence relations are to partitions. Even if we are really only interested in realising a group as a permutation group, group actions are much easier to manipulate, even though the data of a group action is the same as the data of a group homomorphism.

Definition 22.1. Let $S$ be a set and let $G$ be a group.
A group action is a function

$$
G \times S \longrightarrow S \quad \text { given as } \quad(g, s) \longrightarrow g \cdot s
$$

that satisfies
(1) For every $s \in S$ we have

$$
e \cdot s=s
$$

(2) For every $s \in S$ and $g, h \in G$.

$$
(g h) \cdot s=g \cdot(h \cdot s) .
$$

In words, the identity of $G$ acts as the identity on $S$ and to apply $g h$ is the same as to first apply $h$ and then to apply $g$.

Definition-Lemma 22.2. Suppose the group $G$ acts on the set $S$.
Define an equivalence relation $\sim$ on $S$ by the rule $a \sim b$ if and only if there is an element $g \in G$ such that $g \cdot a=b$.

Proof. We have to check that $\sim$ is reflexive, symmetric and transitive.
If $s \in S$ then $e \cdot s=s$ so that $s \sim s$ and $\sim$ is reflexive.
If $s$ and $t \in S$ and $s \sim t$ then we may find $g \in G$ such that $g \cdot s=t$. In this case

$$
\begin{aligned}
g^{-1} \cdot t & =g^{-1} \cdot(g \cdot s) \\
& =\left(g^{-1} g\right) \cdot s \\
& =e \cdot s \\
& =s .
\end{aligned}
$$

Thus $t \sim s$ and $\sim$ is symmetric.

Now suppose $r \sim s$ and $s \sim t$. Then we may find $g$ and $h \in G$ such that $g \cdot r=s$ and $h \cdot s=t$. In this case

$$
\begin{aligned}
(g h) \cdot r & =g \cdot(h \cdot r) \\
& =g \cdot s \\
& =t .
\end{aligned}
$$

Thus $r \sim t$ and $\sim$ is transitive.
Note that in the course of the proof we saw that $g^{-1}$ acts as the inverse of $g$.

Definition 22.3. The equivalence classes of the equivalence relation above are called orbits.

The action is called transitive if there is one orbit.
Proposition 22.4. Let $G$ be a group and let $S$ be a set.
The data of an action of $G$ on $S$ is the same as the data of a representation, a group homomorphism

$$
\phi: G \longrightarrow A(S)
$$

Proof. Suppose we are given an action of $G$ in $S$. If we fix $g$ then we get a function

$$
\sigma: S \longrightarrow S \quad \text { given by } \quad \sigma(s)=g \cdot s
$$

It is easy to see that the inverse of $\sigma$ is given by the action of $g^{-1}$. Thus $\sigma \in A(S)$ is a permutation of $S$. This gives us a function

$$
\phi: G \longrightarrow A(S) \quad \text { given by } \quad \phi(g)=\sigma .
$$

Suppose that $g$ and $h \in G$ and let $\sigma=\phi(g), \tau=\phi(h)$ and $\rho=\phi(g h)$. We check that

$$
\rho=\tau \sigma
$$

Both sides are permutations of $S$ and so it suffices to show they have the same effect on an element $s \in S$. We have

$$
\begin{aligned}
\rho(s) & =(g h) \cdot s \\
& =g \cdot(h \cdot s) \\
& =g \cdot(\sigma(s)) \\
& =\tau(\sigma(s)) \\
& =(\tau \circ \sigma)(s) \\
& =(\tau \sigma)(s) .
\end{aligned}
$$

Thus $\phi$ is a group homomorphism and we get a representation.

Now suppose we are given a representation, a group homomorphism

$$
\phi: G \longrightarrow A(S) .
$$

Define an action

$$
G \times S \longrightarrow S \quad \text { by the rule } \quad g \cdot s=\phi(g)(s)
$$

It is straightforward to check that we do get an action and going backwards and forwards from action to representation are inverses to each other.

Example 22.5. $D_{n}$ acts on the vertices of a regular n-gon.
The action is the obvious one and the action is transitive. The corresponding representation is the standard one.

There are two natural ways a group acts on itself.
Example 22.6. Let $G$ be a group.
$G$ acts on the set $G$ by left translation

$$
G \times G \longrightarrow G \quad \text { given by } \quad g \cdot s=g s
$$

The action is transitive. The corresponding representation is the one given by Cayley's theorem.

More generally, let $H$ be a subgroup of $G$. Then $G$ acts on the left cosets $S$ of $H$ in $G$ in the obvious way

$$
G \times S \longrightarrow S \quad \text { given by } \quad g \cdot(a H)=(g a) H
$$

The action is transitive.
Example 22.7. Let $G$ be a group.
$G$ acts on itself by conjugation

$$
G \times G \longrightarrow G \quad \text { given by } \quad g \cdot s=g s g^{-1} .
$$

Note that the orbits are precisely the conjugacy classes of $G$.
One key property of group actions is that it is easy to count the size of an orbit:

Definition-Lemma 22.8. Suppose the group $G$ acts on the set $S$. Suppose that $s \in S$.

The stabiliser of $s$, denoted $\operatorname{Stab}(s)$, is the subgroup

$$
H=\{g \in G \mid g \cdot s=s .\}
$$

Let $O$ be the orbit of $s$. Then

$$
|O|=[G: H] .
$$

In words the cardinality of the orbit of $s$ is simply the index of the stabiliser of $s$.

In particular the cardinality of an orbit divides the order of $G$.
Proof. We first check that $H$ is a subgroup.
$H$ is non-empty as $e \in H$. We check that $H$ is closed under products and inverses.

Suppose that $g$ and $h \in H$. We have

$$
\begin{aligned}
(g h) \cdot s & =g \cdot(h \cdot s) \\
& =g \cdot s \\
& =s .
\end{aligned}
$$

Thus $g h \in H$ and $H$ is closed under products.
Now suppose that $g \in H$. Then $g \cdot s=s$ so that $g^{-1} \cdot s=s$. Thus $g^{-1} \in H$ and $H$ is closed under inverses. Thus $H$ is a subgroup.

Define a function

$$
f: G \longrightarrow S \quad \text { by the rule } \quad f(g)=g \cdot s
$$

The image of $f$ is the orbit $O$ of $s$. Define a relation $\sim$ on $G$ by the rule $a \sim b$ if and only if $f(a)=f(b)$.

Claim 22.9. $a \sim b$ if and only if $a^{-1} b \in H$.
Proof of 22.9.

$$
\begin{array}{ll}
a \sim b & \text { if and only if } f(a)=f(b) \\
& \text { if and only if } a \cdot s=b \cdot s \\
& \text { if and only if } a^{-1} \cdot(b \cdot s)=s \\
& \text { if and only if }\left(a^{-1} b\right) \cdot s=s \\
& \text { if and only if } a^{-1} b \in H .
\end{array}
$$

Note that the relation $a \sim b$ if and only if $a^{-1} b \in H$ is the relation used to define the left cosets of $H$ in $G$. It follows that the inverse image of point of $O$ is simply a left coset, which has cardinality the order of $H$. Thus the number of elements of $G$ is precisely

$$
|G|=|O| \cdot|H|
$$

Dividing by $|H|$ and using Lagrange we get

$$
|O|=[G: H] .
$$

Example 22.10. Suppose that $G=D_{n}$ and $S$ is the set vertices of a regular n-gon.

Fix a vertex $a$. No rotation fixes $a$ but there is one flip that fixes $a$ (it is the flip that either goes through the opposite vertex, if $n$ is even,
or the opposite edge if $n$ is odd). Thus the stabiliser $H$ of $a$ has two elements.

The action is transitive and $S$ has $n$ elements. On the other hand $D_{n}$ has $2 n$ elements, so that the index of $H$ is also $n$, as expected.

We will need another easy result about group actions:
Lemma 22.11. Suppose that $G$ acts on the set $S$.
If $g \cdot s=t$ then

$$
\operatorname{Stab}(t)=g \operatorname{Stab}(s) g^{-1}
$$

Proof. We show that the RHS is contained in the LHS. Suppose that $h \in \operatorname{Stab}(s)$. We have

$$
\begin{aligned}
\left(g h g^{-1}\right) \cdot t & =\left(g h g^{-1}\right) \cdot(g \cdot s) \\
& =(g h) \cdot\left(\left(g^{-1} g\right) \cdot s\right) \\
& =(g h) \cdot(e \cdot s) \\
& =(g h) \cdot s \\
& =g \cdot(h \cdot s) \\
& =g \cdot s \\
& =t .
\end{aligned}
$$

Thus $g h g^{-1} \in \operatorname{Stab}(t)$ and it follows that

$$
\operatorname{Stab}(t) \supset g \operatorname{Stab}(s) g^{-1}
$$

Now apply the same result to $t$ and $g^{-1}$ to get

$$
\operatorname{Stab}\left(g^{-1} \cdot t\right) \supset g^{-1} \operatorname{Stab}(t) g
$$

Conjugating both sides by $g$ and observing that $s=g^{-1} \cdot t$ gives

$$
\operatorname{Stab}(t) \subset g \operatorname{Stab}(s) g^{-1}
$$

In words, the stabiliser of $g \cdot s$ is the conjugate of the stabiliser of $s$ by $g$.

