

A summary of

## Dynamic location problems with limited look-ahead

by Fan Chung and Ronald Graham

The following problem arose in connection with studies of Internet web page caching. The general setting is as follows:

In some fixed metric space  $M$ ,  $k$  “servers”  $S_1, \dots, S_k$  are given with some arbitrary initial locations in  $M$ . Requests for service at certain points  $\sigma_1, \sigma_2, \sigma_3, \dots, \sigma_N$ , in  $M$  arrive over time. Immediately after request  $\sigma_t$  is received, exactly one of several mutually exclusive actions must be taken:

- (i) Some server is moved to  $\sigma_t$ , with a resulting cost of  $c(\sigma_t)$ , the “cost” of the point  $\sigma_t$ .
- (ii) No server moves. In this case, the cost for “no service” is defined to be  $\min_k d(S_k, \sigma_t)$ , where  $d(x, y)$  denotes the distance between  $x$  and  $y$  in  $M$ .

A further feature of our model is that two parameters  $u, w \geq 0$  are specified, which are used as follows. Before having to decide how to service request  $\sigma_t$ , the servers have at their disposal the knowledge of the  $u + w$  requests  $\sigma_i$  with  $t - u \leq i \leq t + w - 1$ . Thus, the servers can only “remember” or store the past  $u$  requests  $\sigma_{t-u}, \sigma_{t-u+1}, \dots, \sigma_{t-1}$  but are allowed to know the  $w$  future requests  $\sigma_t, \sigma_{t+1}, \dots, \sigma_{t+w-1}$  before having to service  $\sigma_t$ .

The rules which govern the choices made for servicing all the  $\sigma_t$  define some algorithm  $A$ . In this model,  $A$  is deterministic and can only depend on the values of the  $\sigma_i$  which it currently knows, and nothing else. In particular,  $A$  is not allowed to make probabilistic choices based on some source of randomness. We denote by  $A(\sigma)$ , the cost of servicing the request sequence  $\sigma = (\sigma_1, \dots, \sigma_N)$ .

Of course, if we are allowed to know *all* the  $\sigma_t$  before having to act, it is very likely the cost of servicing  $\sigma$  can be decreased. Let us denote by  $\text{OFF}(\sigma)$  the minimum possible cost of servicing  $\sigma$  in this case. Thus,  $\text{OFF}(\sigma)$  is the cost for an optimal *off-line* algorithm for  $\sigma$ .

The problem of interest here is to investigate the effect of being able to look ahead (as well as utilizing the past history) on the performance of such algorithms.

For a given request sequence, let  $\text{OPT}^{(u,w)}(\sigma)$  denote the minimum cost of any  $(u, w)$ -window algorithm servicing  $\sigma$ , and we define

$$\rho(u, w) : = \inf_{\sigma} \frac{\text{OPT}^{(u,w)}(\sigma)}{\text{OFF}(\sigma)}$$

over all  $\sigma$  with  $\text{OFF}(\sigma) \rightarrow \infty$  to avoid certain inessential degeneracies. (In our model, we are assuming our “adversary”, i.e., the source generating the request sequence  $\sigma$ , is all-powerful. That is, the adversary knows everything about the servers’ strategy and can predict everything they will do.) The basic problem then is to understand how  $\rho(u, w)$  is affected by the various parameters in our model, i.e., the metric space  $(M, d)$ , and the choice of the cost function  $c$ .

This model can be further extended by allowing “excursions”, i.e., where servers are allowed to go to arbitrary points in  $M$  in response to a request  $\sigma_t$ . In other words, we can replace (i) by :

- (i’) Some server, say  $S_i$ , is moved to some vertex  $v$ , with a resulting cost of  $c(v) + d(S_i, v) + d(v, \sigma_t)$ .

We note that a fair amount is known when option (ii) is not allowed,  $w = 1$ , and the cost function  $C$  depends on  $d(S_i, \sigma_t)$  and not just  $\sigma_t$ . In other words, some server must always be moved to the current request, but the cost only depends on the distance moved (see [2] or [7] for a survey). It is shown in [5] that for this model, finite look-ahead does not help

asymptotically. However, for the model of allowing excursions, finite values of  $w$  do make a difference.

By examining several special cases of the general problem, there is an example of the “windex phenomenon”. That is, we have  $\rho(0, 4) = 3 = \rho(t, 0)$  for all  $t \geq 4$ . In other words, if you can’t see into the future at all, then it doesn’t help to see more than four steps into the past. Does this phenomenon occur for all  $w < \infty$ ? Is there an efficient algorithm for determining  $\rho(u, w)$  for given large values of  $u$  and  $w$ ? What happens for varying costs  $c(o)$  and  $c(1)$ ? On more general graphs? With  $k > 1$  servers? These questions among many others (unfortunately ) illustrate how incomplete our knowledge is here at this point in time.

## References

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