

Notes: 1. Any open set is a manifold:

$$U \subset \mathbb{R}^n \quad f: U \longrightarrow \{0\} = \mathbb{R}^0$$

graph of f : $\Gamma(f) \subset \mathbb{R}^n \times \mathbb{R}^0 = \mathbb{R}^n$

$$\stackrel{||}{=} \left\{ (v, 0) : f(v) = 0 \right\} = \{(v, 0)\}$$

$$= U \times \{0\} \subset \mathbb{R}^n \times \{0\}$$

$$\stackrel{||}{=} U$$

$$\stackrel{||}{=} \mathbb{R}^n$$

$$g: U \times \{0\} \longrightarrow U \quad \text{bijection}$$

$$(v, 0) \longmapsto v$$

$$(v, 0) \longleftarrow v$$

2. Closed sets are NOT always manifolds.

Zeros of continuous functions are examples of closed sets:

e.g. (a) $f(x, y) = y - x^2$

$$Z(f) = \{y = x^2\} \text{ parabola}$$

smooth manifold because it is the graph of the

C^1 function $g(x) = x^2$.

(b) $f(x, y) = |x| - y, Z(f) = \{f(x, y) = 0\}$ is a graph

but $g(x) = |x|$ is NOT C^1

$$Z(f) = \{|x| - y = 0\} = \Gamma(g)$$

$$(c) \quad F(x, y) = (x^2 + y^2 - 1)^3$$

F is differentiable because it is a polynomial

$$\frac{\partial F}{\partial x} = 3 \cdot 2x \cdot (x^2 + y^2 - 1)^2$$

$$\frac{\partial F}{\partial y} = 3 \cdot 2y \cdot (x^2 + y^2 - 1)^2$$

on $Z(F)$, we have $\frac{\partial F}{\partial x} = \frac{\partial F}{\partial y} = 0$

put $f(x, y) = x^2 + y^2 - 1$, then

$$Z(F) = Z(f)$$

$$3. \quad F: \mathbb{R}^n \longrightarrow \mathbb{R}^{n-k}$$

$$F = \begin{pmatrix} F_1 \\ \vdots \\ F_{n-k} \end{pmatrix}$$

$$Z(F) = Z(F_1) \cap Z(F_2) \cap \dots \cap Z(F_{n-k})$$

$$DF(a) = \begin{pmatrix} DF_1(a) \\ \vdots \\ DF_{n-k}(a) \end{pmatrix} : \mathbb{R}^n \longrightarrow \mathbb{R}^{n-k}$$

$$DF_1(a) : \mathbb{R}^n \longrightarrow \mathbb{R}$$

$$DF(a) \text{ surjective } (\Leftrightarrow) \dim(\ker DF(a)) = k$$

$$DF_1(a) \text{ surjective } (\Leftrightarrow) \dim(\ker DF_1(a)) = n-1$$

$$\ker DF(a) = \ker DF_1(a) \cap \ker DF_2(a) \cap \dots \cap \ker DF_{n-k}(a).$$

(7) Our preparation (practice) sheet:

$$\begin{cases} x^2 + y^2 + z^2 - yw = 2 \\ xyw - yz + z^2 + w^2 = 0 \end{cases}$$

$(0, 1, 1, 0)$ satisfies the system: plug in. ✓

$$F : \mathbb{R}^4 \longrightarrow \mathbb{R}^2 \quad 2 = n - k \quad 4 = n \quad \Rightarrow \quad k = 2$$

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \longmapsto \begin{pmatrix} x^2 + y^2 + z^2 - yw - 2 \\ xyw - yz + z^2 + w^2 \end{pmatrix}$$

$Z(F)$?

F is C^1 : the components are polynomials.

$$JF = \begin{pmatrix} 2x & 2y-2w & 2z & -2 \\ yw & xw-z & 2z-y & xy+2w \end{pmatrix}$$

$$JF \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 & 2 & 2 & -1 \\ 0 & -1 & 1 & 0 \end{pmatrix}$$

Any two of the last 3 columns are linearly independent. So, in a neighborhood of $\begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix}$, we can write (y, z) as a function of (x, w)

or (y, w) as a function of (x, z)

or (z, w) as a function of (x, y)

We pick the last possibility: \exists function $g(x, y)$ s.t. in a neighborhood of $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$,

$$(z, w) = g(x, y) \iff F(x, y, z, w) = 0$$

α in a neighborhood of $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$: $\Gamma(g) = \Sigma(F)$

α $\forall (x, y)$ in a neighborhood of $(0, 1)$

$$F(x, y, g_1(x, y), g_2(x, y)) = 0$$

where $g = \begin{pmatrix} g_1 \\ g_2 \end{pmatrix}$

The implicit function theorem says g is C^1 in a small neighborhood of $(0, 1)$.

We can ask where, a particular set of variables can be expressed as functions of the others.

e.g. : where can (y, z) be locally expressed as functions of (x, w) ? This is the locus where the

columns corresponding to y and z are linearly independent, i.e., the submatrix

$$\begin{pmatrix} 2y - w & 2z \\ xw - z & 2z - y \end{pmatrix} \text{ has rank 2.}$$

The determinant is $(2y - w)(2z - y) - 2z(xw - z)$

The matrix has rank 2 when the determinant is not 0.

So, if $(2y-w)(2z-y) - 2z(xw-z) \neq 0$, and $F(x, y, z, w) = 0$, we can locally express (y, z) as a function of (x, w) .

If (e.g.) we just had $F(x, y, z, w) = x^2 + y^2 + z^2 - yw - z$.

then, we could look at $DF(a_1, \dots, a_4)$

$$DF = \begin{pmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} & \frac{\partial F}{\partial z} & \frac{\partial F}{\partial w} \end{pmatrix}$$

$$F: \mathbb{R}^4 \rightarrow \mathbb{R}$$

$$DF(0, 1, 1, 0): \mathbb{R}^4 \rightarrow \mathbb{R}$$

$$DF(0, 1, 1, 0) = (0 \quad 2 \quad 2 \quad -1)$$

$\frac{\partial F}{\partial y}(0, 1, 1, 0) \neq 0 \Rightarrow y$ is locally an implicit function of (x, z, w) near $(0, 1, 1, 0)$

Similarly, z can be locally expressed as a function of x, y, w .

And w can be locally expressed as a function of x, y, z .

derivative of $g: \frac{\partial}{\partial x} \left(F(x, y, g_1(x, y), g_2(x, y)) \right) = 0$.

$$\frac{\partial F}{\partial x}(a) + \frac{\partial g_1}{\partial x}(?) \frac{\partial F}{\partial y}(a) + \frac{\partial g_2}{\partial x}(?) \frac{\partial F}{\partial w}(a) = 0$$

The tangent vector space to $Z(F)$ at $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ is the kernel of $DF \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ represented by the matrix $\begin{pmatrix} 0 & 2 & 2 & -1 \\ 0 & -1 & 1 & 0 \end{pmatrix}$

The kernel of this is the set of (x, y, z, w) s.t.

$$\begin{pmatrix} 0 & 2 & 2 & -1 \\ 0 & -1 & 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = 0 \quad \text{or:} \quad \begin{cases} 2y + 2z - w = 0 \\ -y + z = 0 \end{cases}$$

The equation of the tangent affine space is the set of (x, y, z, w) s.t. $\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix}$ belongs to the

tangent vector space:

$$\begin{cases} 2(y-1) + 2(z-1) - w = 0 \\ -(y-1) + (z-1) = 0 \end{cases}$$

Definition and Proposition (3.2.9 C^k map on a manifold and its derivative)

Let $M \subset \mathbb{R}^n$ be a k -dimensional smooth manifold.

A map $f: M \rightarrow \mathbb{R}^m$ is of class C^k if every $x \in M$ has an open neighborhood $U \subset \mathbb{R}^n$ s.t. \exists a map $\tilde{f}: U \rightarrow \mathbb{R}^m$ of class C^k with $\tilde{f}|_{U \cap M} = f|_{U \cap M}$

(this means that, for all $y \in U \cap M$, $\tilde{f}(y) = f(y)$)

Furthermore, if $k \geq 1$, the derivative of f at x is defined to be $Df(x) := D\tilde{f}(x)|_{T_x M} : T_x M \rightarrow \mathbb{R}^m$

(this means that $Df(x)$ is only well-defined on the tangent vector space $T_x M$ and $\forall v \in T_x M$, $(Df(x))(v) = (D\tilde{f}(x))(v)$)

$Df(x): T_x M \rightarrow \mathbb{R}^m$ only depends on f and not on the choice of \tilde{f} .