

We finish the computation of the total derivative  
 for the example  $f\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x^2 + 1 + y \\ \sin(xy) \\ e^x - e^y \end{pmatrix}$

$$h_2 := \frac{1}{|h|} \left( \sin((x+h_1)(y+h_2)) - \sin(xy) - y \cos(xy) h_1 - x \cos(xy) h_2 \right)$$

One way to compute this limit is to use the Maclaurin series for sine and cosine.

$$e^{i\theta} = \cos \theta + i \sin \theta$$

$$e^{i\theta} = 1 + i\theta + \frac{(i\theta)^2}{2!} + \frac{(i\theta)^3}{3!} + \frac{(i\theta)^4}{4!} + \frac{(i\theta)^5}{5!} + \frac{(i\theta)^6}{6!} + \dots$$

$$\Rightarrow \cos \theta = 1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \frac{\theta^6}{6!} + \dots$$

$$\sin \theta = \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \frac{\theta^7}{7!} + \dots$$

$$h_2 = \frac{1}{|h|} \left( (x+h_1)(y+h_2) - \frac{(x+h_1)^3 (y+h_2)^3}{3!} + \dots - xy + \frac{x^3 y^3}{3!} - \dots - y \left( 1 - \frac{(xy)^2}{2!} + \frac{(xy)^4}{4!} - \dots \right) h_1 - x \left( 1 - \frac{(xy)^2}{2!} + \frac{(xy)^4}{4!} - \dots \right) h_2 \right)$$

First:  $(x+h_1)(y+h_2) - xy - yh_1 - xh_2 = h_1 h_2$

degree 3:  $-\frac{(x^3 + 3x^2 h_1 + \dots)(y^3 + 3y^2 h_2 + \dots)}{3!} - \frac{x^3 y^3}{3!} + y \frac{x^2 y^2 h_1}{2} + \dots + x \frac{x^2 y^2 h_2}{2} + \dots$

In all degrees the terms that have degree  $\leq 1$  in  $h_1$  or  $h_2$  cancel each other, so we only have terms of degree  $\geq 2$  in  $h_1, h_2$ .

$$\text{So } b_2 = \frac{1}{|h|} \left( h_1^2 A(h_1, h_2, x, y) + h_1 h_2 B(h_1, h_2, x, y) + h_2^2 C(h_1, h_2, x, y) \right)$$

$A, B, C$  are continuous functions for all  $h_1, h_2, x, y$  because they are obtained from the everywhere absolutely convergent power series for sine and cosine.

$$\text{and } \lim_{h \rightarrow 0} \frac{h_1^2}{|h|} = \lim_{h \rightarrow 0} \frac{h_1 h_2}{|h|} = \lim_{h \rightarrow 0} \frac{h_2^2}{|h|} = 0$$

$$\text{So } \lim_{h \rightarrow 0} b_2 = 0$$

$$b_3 := \frac{1}{|h|} \left( e^{x+h_1} e^{y+h_2} - e^x + e^y - e^x h_1 + e^y h_2 \right)$$

$$r_3 = \frac{1}{|h|} \left( e^x (e^{h_1} - 1 - h_1) - e^y (e^{h_2} - 1 - h_2) \right)$$

$$e^{h_1} = 1 + h_1 + \frac{h_1^2}{2!} + \dots$$

$$\Rightarrow e^{h_1} - 1 - h_1 = h_1^2 A(h_1)$$

$$e^{h_2} - 1 - h_2 = h_2^2 B(h_2)$$

$$r_3 = \frac{1}{|h|} \left( e^x h_1^2 A(h_1) - e^y h_2^2 B(h_2) \right)$$

As before,  $\lim_{h \rightarrow 0} r_3 = 0$

# Directional derivatives:

$U \subset \mathbb{R}^n$  open  $f: U \rightarrow \mathbb{R}^m$  function.

$$f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$$

recall  $\frac{\partial f_i}{\partial x_j} = \lim_{h_j \rightarrow 0}$

$$\frac{f_i \begin{pmatrix} x_1 \\ \vdots \\ x_j + h_j \\ \vdots \\ x_n \end{pmatrix} - f_i \begin{pmatrix} x_1 \\ \vdots \\ x_j \\ \vdots \\ x_n \end{pmatrix}}{h_j}$$

of  $a = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

and  $e_1, \dots, e_n$  is the standard basis for  $\mathbb{R}^n$

then  $\begin{pmatrix} x_1 \\ \vdots \\ x_j + h_j \\ \vdots \\ x_n \end{pmatrix} = a + h_j e_j$  and  $|h_j| = |h_j e_j|$

The partial derivative

$$\frac{\partial f}{\partial x_j}$$

is

$$\begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_j} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix}$$

is a special case of a directional derivative.

$\mathcal{H}$  is the directional derivative in the direction of  $e_j$ . More generally, we have

Def 1.7.13:  $U \subset \mathbb{R}^n$  open  $f: U \rightarrow \mathbb{R}^m$  a function.

$0 \neq v \in \mathbb{R}^n$  a vector. The directional derivative of  $f$  in the direction of  $v$ , if it exists, is

$$\lim_{h \rightarrow 0} \frac{f(a + hv) - f(a)}{h}$$

Proposition 1.7.14:  $U \subset \mathbb{R}^n$  open  $f: U \rightarrow \mathbb{R}^m$  a function.

If  $f$  is differentiable at  $a \in \mathbb{R}^n$ , then all directional derivatives at  $a$  exist and, for  $v \in \mathbb{R}^n$ , the directional derivative in the direction of  $v$  is

$$\lim_{h \rightarrow 0} \frac{f(a+hr) - f(a)}{h} = (Df(a))(v)$$

---

Remark: We can write the directional derivative, when it exists, as  $D_v(f)(a)$  or  $\frac{\partial f}{\partial v}(a)$  or  $\partial_v f(a)$

---

Proof of the Proposition: We know:

$$\lim_{h \rightarrow 0} \frac{1}{|h|} (f(a+h) - f(a) - (Df(a))h) = 0$$

$$\text{So } \lim_{h \rightarrow 0} \frac{1}{|hv|} \left( f(a+hv) - f(a) - (Df(a))(hv) \right) = 0$$

$$\parallel$$
$$\lim_{h \rightarrow 0} \frac{1}{|h||v|} \left( f(a+hv) - f(a) - h (Df(a))(v) \right) = 0$$

$|v|$  is a nonzero constant, so:

$$\lim_{h \rightarrow 0} \frac{1}{|h|} \left( f(a+hv) - f(a) - h Df(a)(v) \right) = 0$$

and  $\lim_{h \rightarrow 0} \frac{1}{h} \left( f(a+hv) - f(a) - h Df(a)(v) \right) = 0$

$\Rightarrow \lim_{h \rightarrow 0} \frac{1}{h} \left( f(a+hv) - f(a) \right)$  exists and is equal to  $Df(a)(v)$ .  $\square$



Sometimes the Jacobian matrix is too complicated.

We can sometimes compute total derivatives in different ways.

e.g.:  $f: M_n(\mathbb{R}) \longrightarrow M_n(\mathbb{R})$

$$\begin{array}{ccc} \mathbb{R}^{n^2} & & \mathbb{R}^{n^2} \\ \uparrow & & \uparrow \\ A & \longmapsto & A^2 \end{array}$$

How do we guess the answer:

$$\lim_{H \rightarrow 0} \frac{1}{|H|} (f(A+H) - f(A) - L(H)) = 0 \quad ?$$

$$\begin{aligned} f(A+H) - f(A) &= (A+H)^2 - A^2 = A^2 + AH + HA + H^2 - A^2 \\ &= AH + HA + H^2 \end{aligned}$$